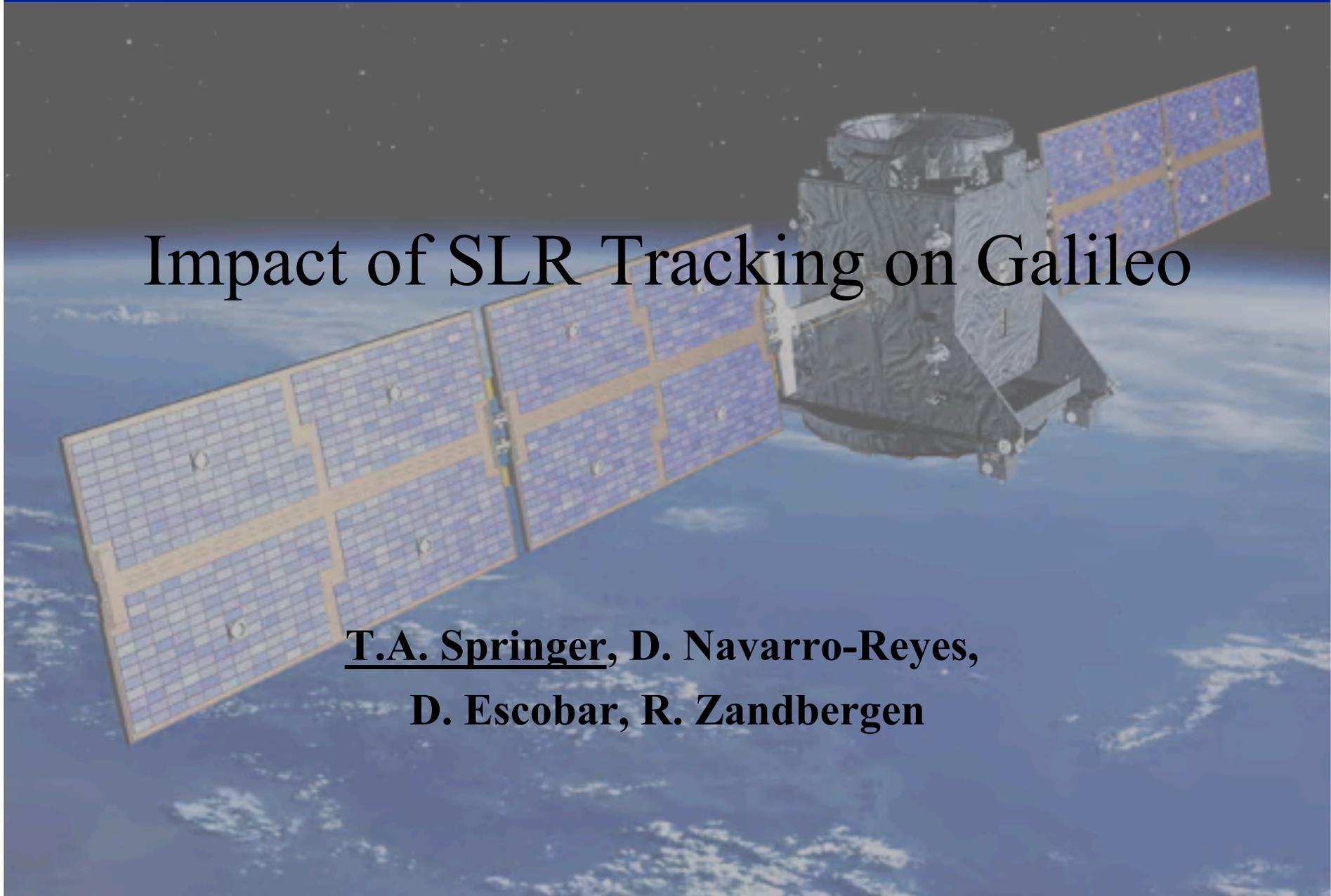


Impact of SLR Tracking on Galileo

**T.A. Springer, D. Navarro-Reyes,
D. Escobar, R. Zandbergen**

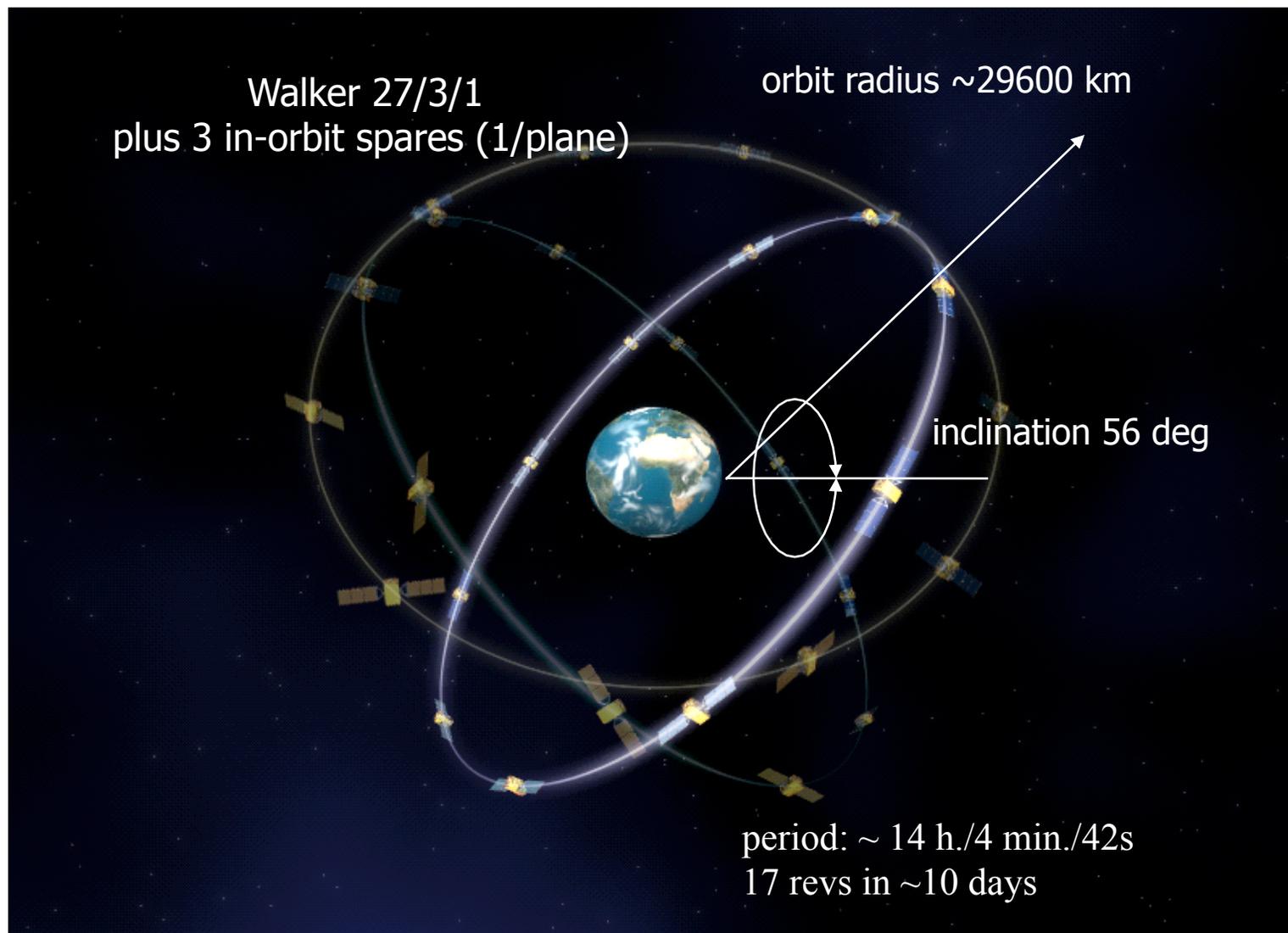


- **Prime design criteria**

- Avoid “station keeping” orbital maneuvers during the spacecraft lifetime
 - ✓ Avoid the “deep 1:2 resonance” from the GPS satellites

- **Constellation Features**

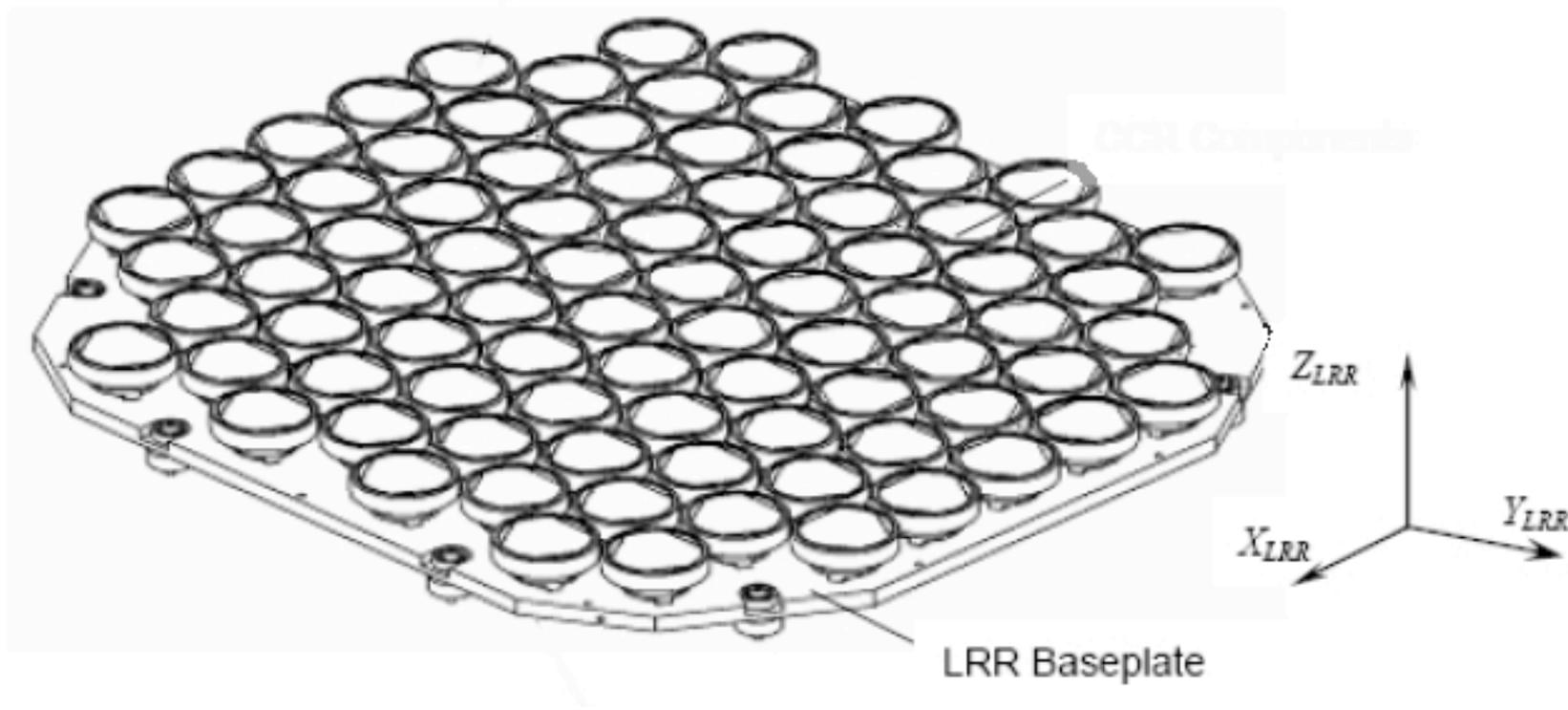
- So called “Walker 27/3/1” constellation
- Almost circular orbit
 - ✓ Orbit Radius ~29'600 km (above GLONASS and GPS)
- Orbit repeat period 10 days
 - ✓ 17 revolutions in 10 days, ~14 hour per revolution
- Inclination 56 degrees
- Three equally spaced orbital planes
- Nine operational satellites, equally spaced in each plane
 - ✓ Plus one spare satellite in each plane



- **Dimensions**
 - 2.5 x 1.2 x 1.1 m
- **Length (Y-axis) 19 m with deployed solar arrays**
- **Spacecraft weight: ~700kg**
- **Power: ~ 1.5 kW**
- **Navigation payload: ~130kg**
- **Power consumption: 900 W**
- **Launcher options**
 - Ariane-5
 - Proton
 - Soyuz (from Kourou)
 - Zenit.

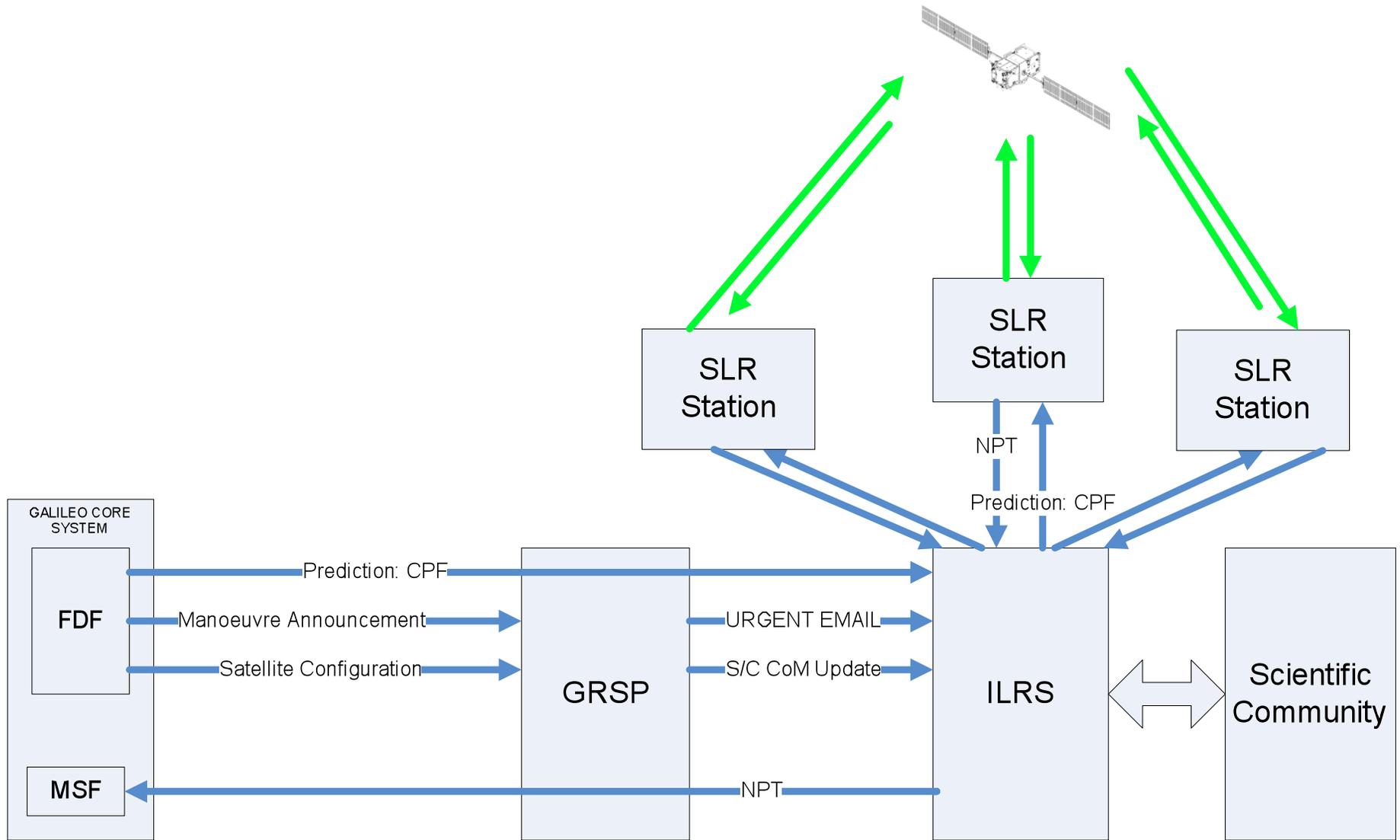


- **Support to Galileo for early phases**
 - With low number of GSS and few IGS Galileo stations GNSS based orbits of Galileo will be of medium accuracy
 - Addition of SLR observation will offer a significant accuracy improvement
- **Calibration of Spacecraft Dynamics**
 - The Y-bias as present on most GNSS satellites has a long term effect on the satellite position.
 - The accurate determination of the Y-bias for each Galileo satellite will be of prime importance to fulfill the “once in a lifetime“ station keeping manoeuvre requirement
- **Alignment of GTRF to ITRF**



Size of Array $\sim 0.35 \times 0.35 \text{ m} = 0.12 \text{ m}^2$

- **84 Corner Cube Reflectors (CCR)**
 - doped fused silica glass tetrahedron
 - no metallic coating
 - aperture face is included in a circle of 43 mm diameter
 - height of the tetrahedron is 23.3 mm
 - Iso-static mounting to plate
 - $N = 1.46$, critical angle 16.9°
 - ✓ which covers the entire LRR operating range (Earth radius of 12.44°)
 - ✓ no coating, total reflection is obtained without any loss
 - Velocity aberration compensation $24 \mu\text{rad}$
 - CCR are randomly oriented
 - LRA Centre of Phase TBD after Qualification Tests
- **This information will be published in an update to “Specification of Galileo and GIOVE Space Segment Properties Relevant for Satellite Laser Ranging” (ESA-EUING-TN-10206) and in the “Mission Support Request Form”**



- **Support to Galileo for early phases**
 - Support for satellite “fine positioning“
 - Support for Galileo operational POD
- **Completely independent validation**
- **Calibration and validation of spacecraft dynamics**
- **Alignment of GTRF to ITRF**
- **Maintain and improve the ITRF**
- **Ensure the position of Galileo**
- **Position Galileo as „best“ GNSS system**
 - No SLR LRA's on GPS
 - „split“ LRA's on GLONASS
- **Ensure GNSS interoperability through a common independent measurement technique**