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# On-orbit Testing of **GOES-16** and **GOES-17 GLM payloads** from 2 NASA SLR sites with collocated laser beacons

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# Optical Lightning - Detection

1. **Lightning from Space:** Lightning appears like a pool of light on the top of the cloud.
2. **Daytime Challenge:** During day, sunlight from cloud top dominates the lightning signal.

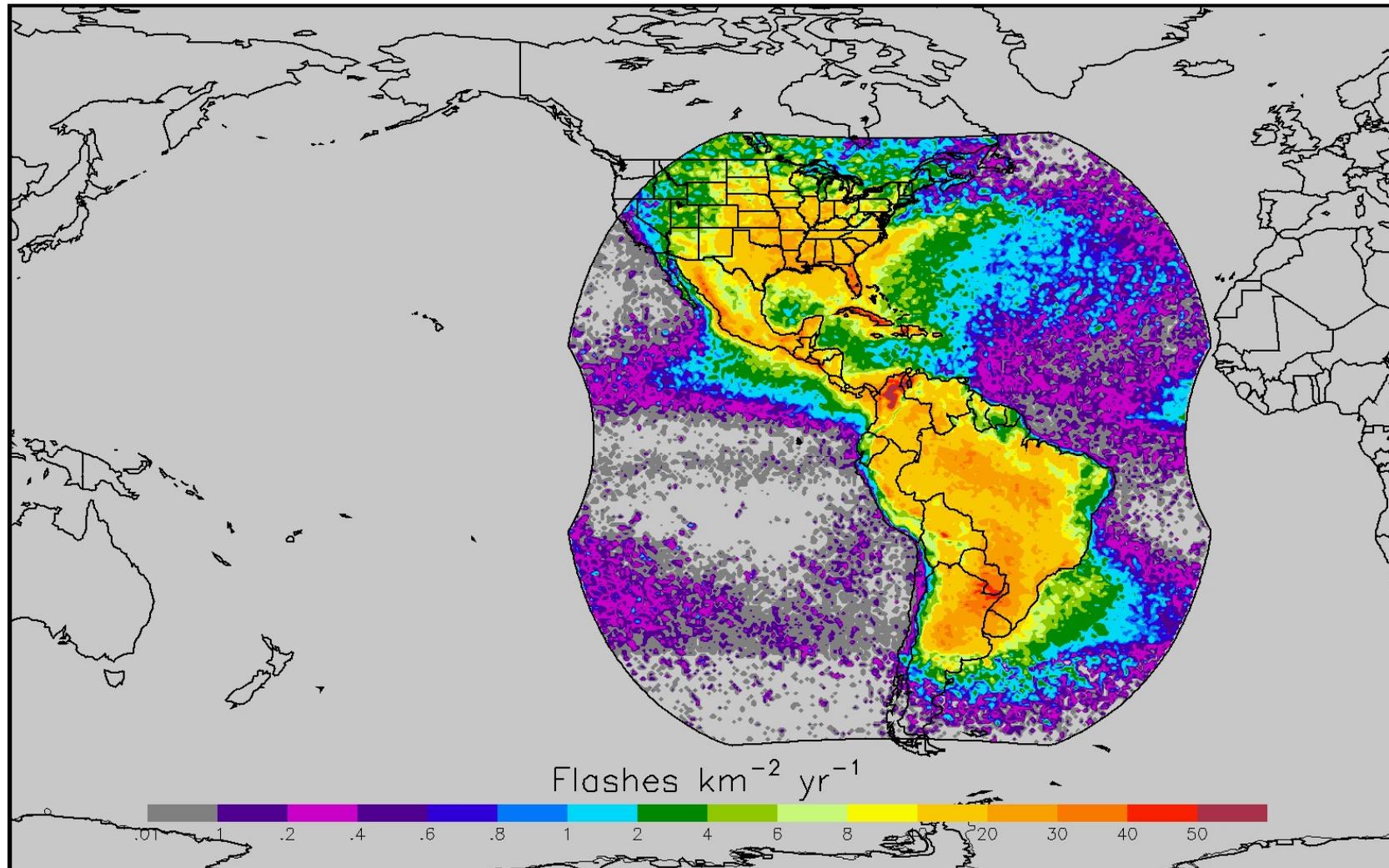


<p><b>Spatial</b></p> <p>Optimal sampling of lightning scene relative to background scene.</p> <p>Pixel field-of-view 4-10 km.</p>	<p>BACKGROUND CLOUD SCENE</p>	<p><b>Spectral</b></p> <p>Optimal sampling of lightning signal relative to background signal.</p> <p>GLM uses 1nm filter at 777.4 nm.</p>	<p>Cloud - Top Lightning Spectrum At Near - Infrared Wavelengths</p> <p>SOLAR RADIATION</p> <p>WAVELENGTH (nm)</p>	<p><b>Temporal</b></p> <p>Optimal sampling of lightning pulse relative to background signal.</p> <p>GLM uses 2 ms frame rate.</p>	<p>FRAME TIME 1 ms</p> <p>800 μs</p> <p>400 μs</p> <p>PEAK</p> <p>0.9</p> <p>0.5</p> <p>0.1</p> <p>AMPLITUDE</p> <p>OPTICAL PULSE DURATION</p> <p>TIME</p>
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- a. Even with **spatial, spectral** and **temporal filters**, **background** can exceed lightning signal by 100 to 1;
- b. **Frame-by-frame background subtraction** to produce a lightning only signal.
- c. **Filtering results in 10<sup>5</sup> reduction** in data rate requirements while maintaining high detection efficiency for lightning.

<p><b>Background Subtraction</b></p> <p>Optimal subtraction of background signal levels at each pixel.</p> <p>Transient events selected for processing.</p>	<p>FLUCTUATING BACKGROUND SIGNAL LEVEL</p> <p>LIGHTNING SIGNAL SUPERIMPOSED WITH BACKGROUND</p> <p>LIGHTNING SIGNAL AFTER BACKGROUND SUBTRACTION</p> <p>SIGNAL LEVEL</p> <p>TIME</p> <p>Input Signal: Background Scene + Optical Transients</p> <p>Averaged Background</p> <p>+</p> <p>-</p> <p>Optical Transients</p> <p>Programmable Threshold</p> <p>Optical Transients</p> <p>COMPARATOR</p> <p>A &gt; B</p> <p>B &gt; A</p> <p>Qualified Lightning Events</p> <p>(a)</p> <p>(b)</p>
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# Lightning Flashes in the Americas



Lightning flash plot based on the LIS/OTD **yearly climatology data**

# GOES R series footprint



## Two operational satellites and on-orbit spare

1. GOES-16, was launched in Nov, 2016 and GOES-17 in March 2018.

# GLM – Rationale for Laser beacon

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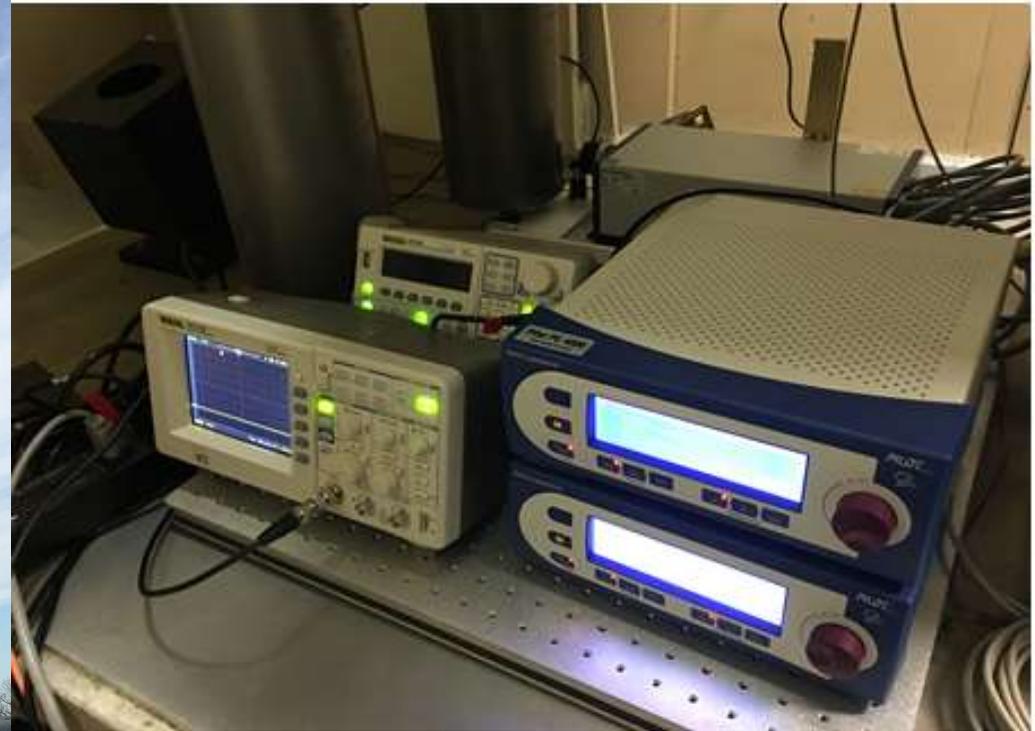
1. GLM needs accurate mapping of its sensor pixels to geo-spatial coordinates. This is needed day and night
2. GPA uses the background images to determine the offset wrto nadir position of the S/C based on a 7 day average.
3. The instrument geospatial accuracy depends on:
  1. Diurnal and thermal dependencies;
  2. “Cloudbottom” model;
  3. Sensor’s “overshoot” correcting digital filter;
  4. Dither, Equinox, Yaw Flip related changes;
  5. Baseline for future.

# GLM - Laser Beacon & Auxiliary optics

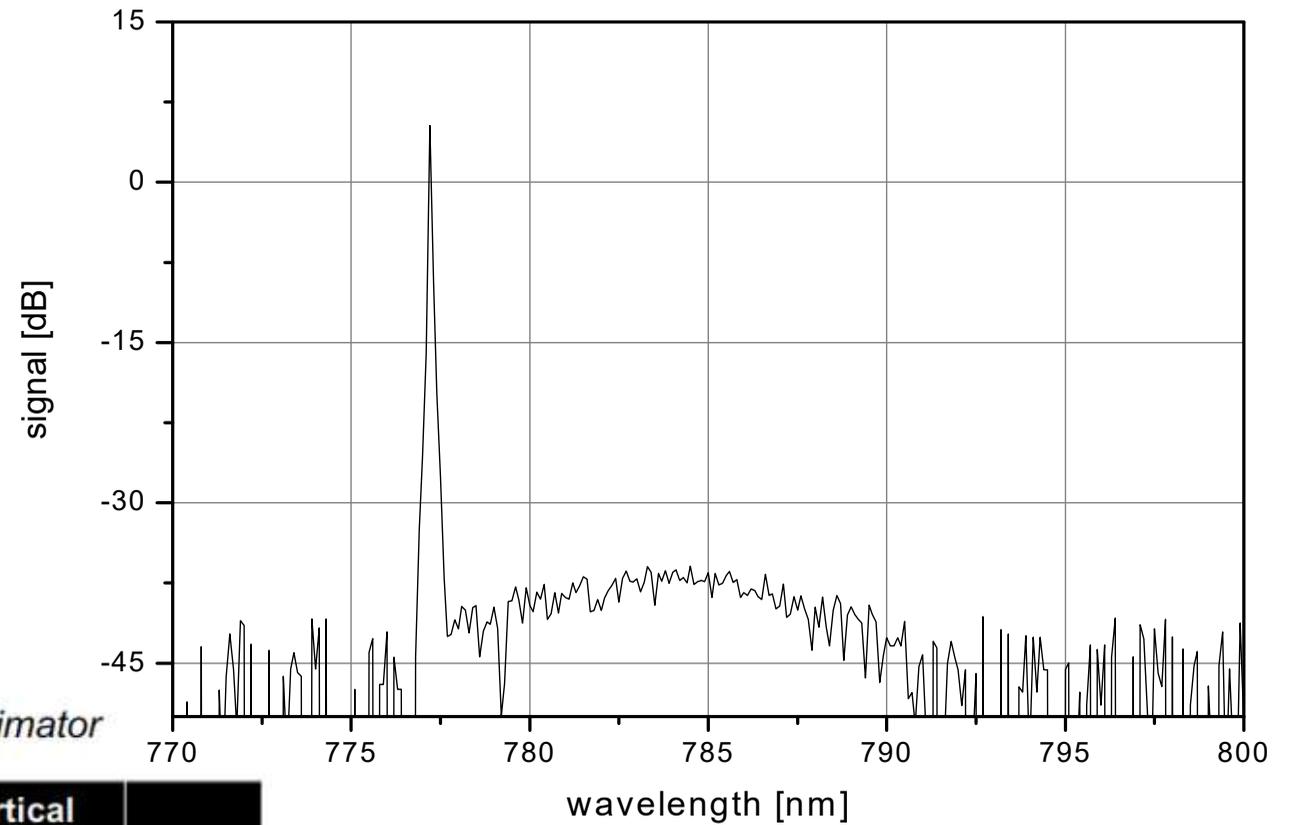
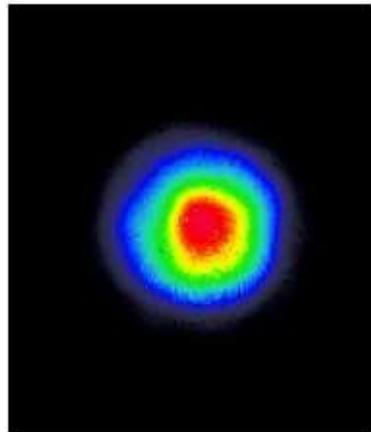
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1. A semiconductor MOPA diode laser at 777.2 nm wavelength;
2. Electronically modulated to produce a 0.5-1.5 ms pulse;
3. Wavelength tuning within 20pm;
4. Laser at a PRF=50Hz;
5. An auxiliary refractive optics telescope + a single mode fiber coupler
6. Piggybacked to the main telescope and co-integrated;
7. Safety system with the added logic for a SINGLE LASER ONLY firing at a time.

# Laser beacon – SLR mounted payload + laser Controls



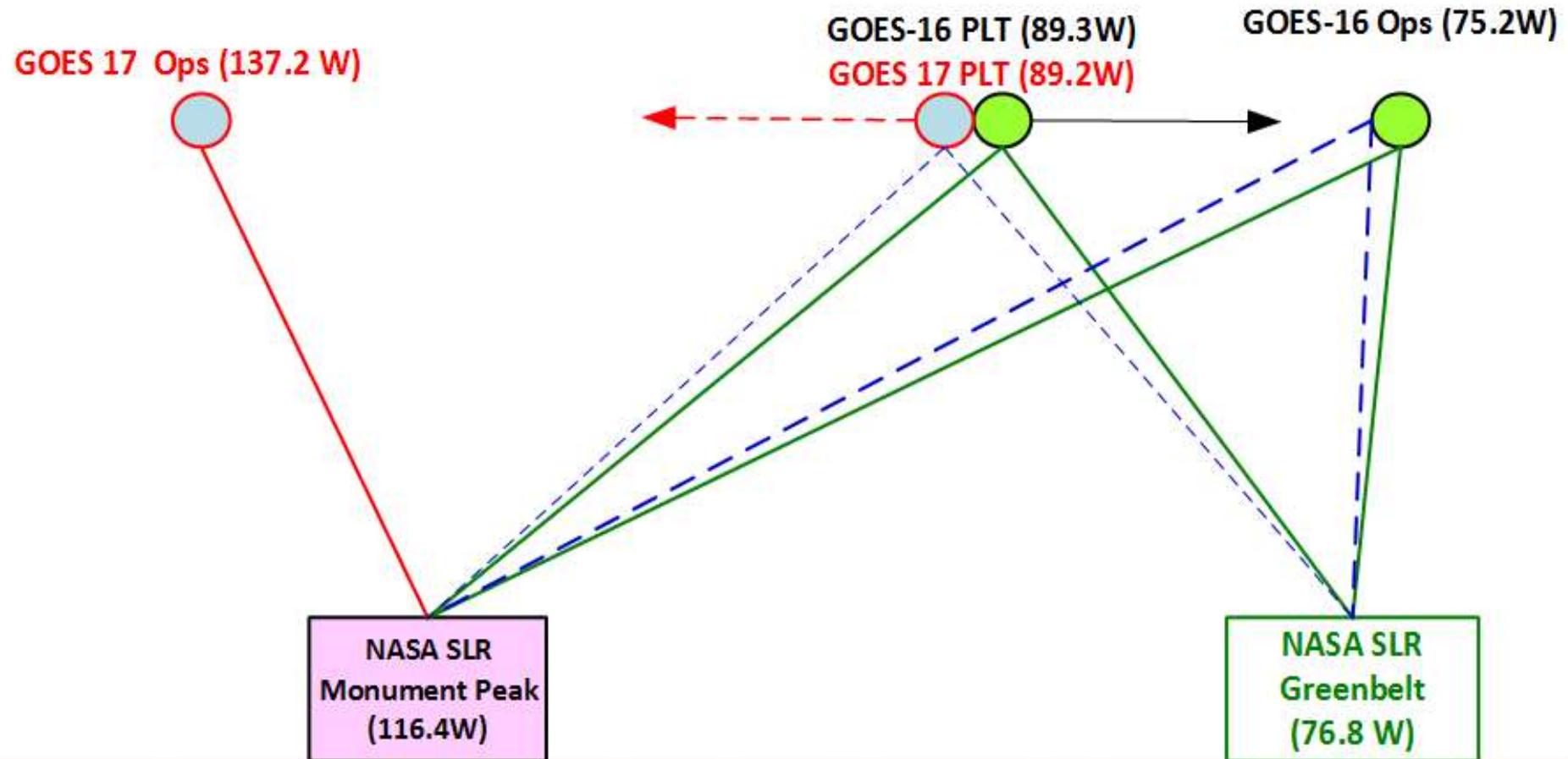
# GLM laser – Key attributes



*Data collected behind fiber collimator*

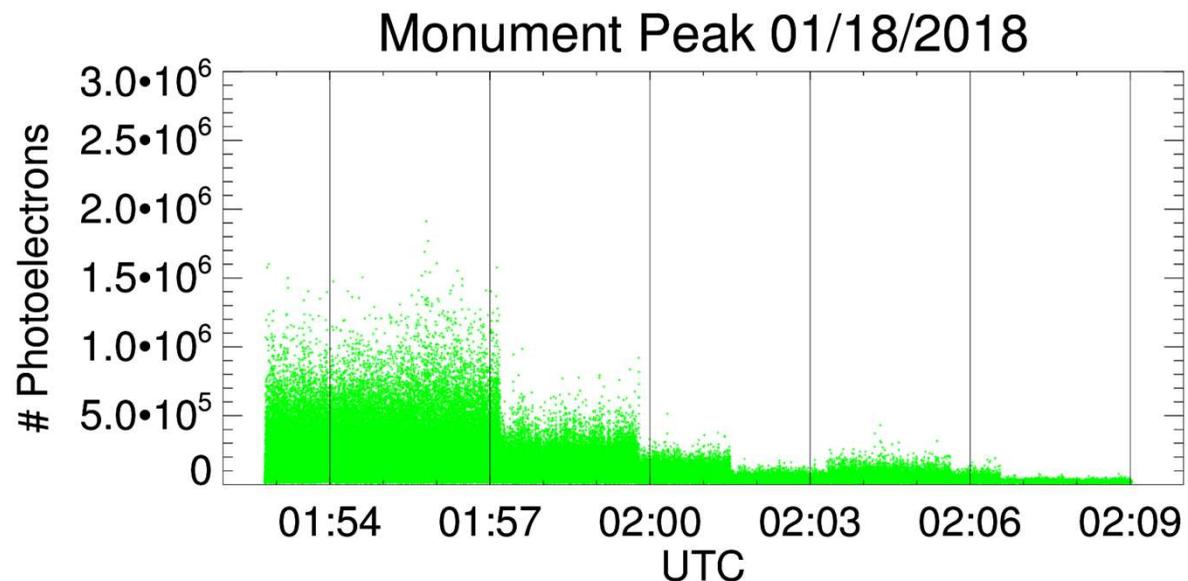
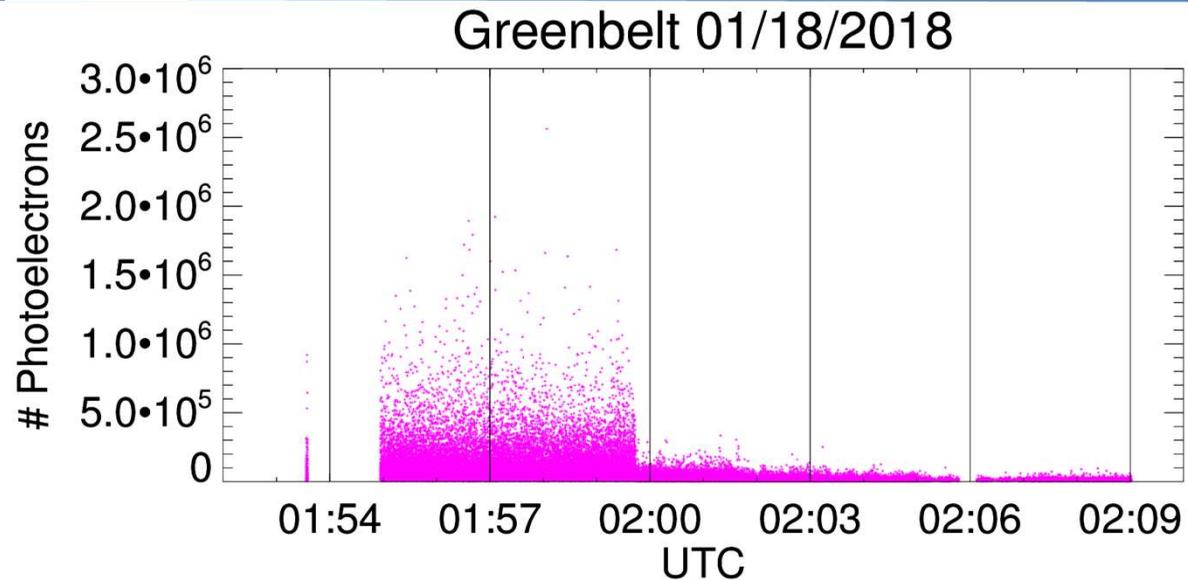
		horizontal	vertical	
Beam quality	M <sup>2</sup>	1.03	1.07	
Astigmatism				1.2%

# Intercomparison Test - Satellites and Sites



**Green line** – data already taken by GOES-16 at the PLT(=89.5W) and Ops slots (=75.2W);  
**Blue dotted line** – Proposed GOES-16 and GOES-17 near simultaneous data collection;  
**Red line** - Data to be taken from the GOES-17 Operational slot; **GB** = Greenbelt;  
**MP**= Monument Peak;

# Laser Beacon Results: Time Series



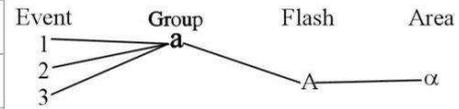
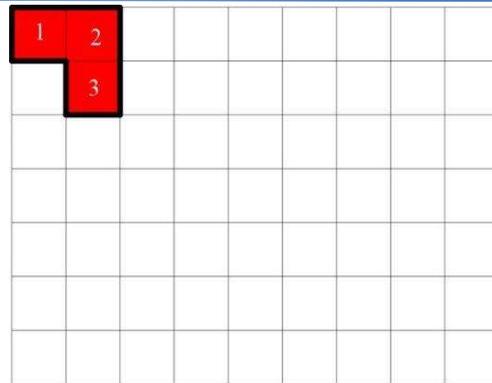
Magenta for Greenbelt;

Green for Monument Peak;

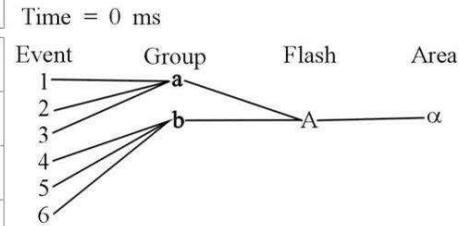
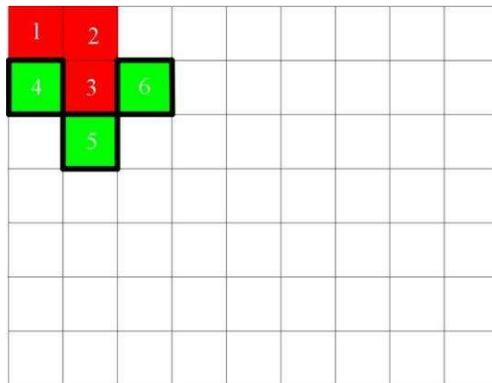
**Raw Data:** Near simultaneous sensor data from 7105 and 7110 sites with  $>1E+5$  pe;

adequate for a robust centroid estimation of the pixel location;

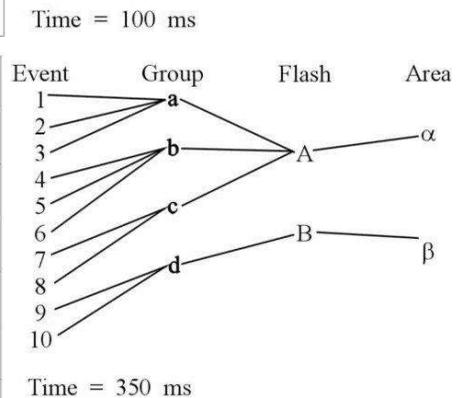
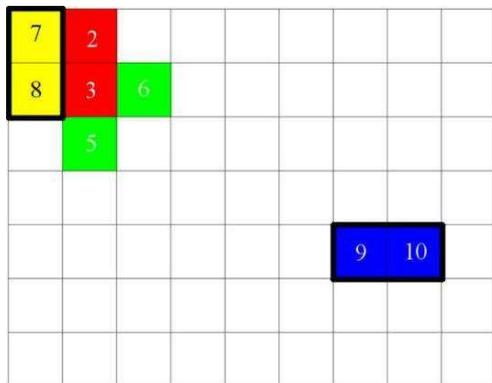
# Data Analysis - Events to Groups to Flashes



**Groups** - Events that occur at same frame time in adjacent pixels



**Flashes** - Groups that occur close together in space and time



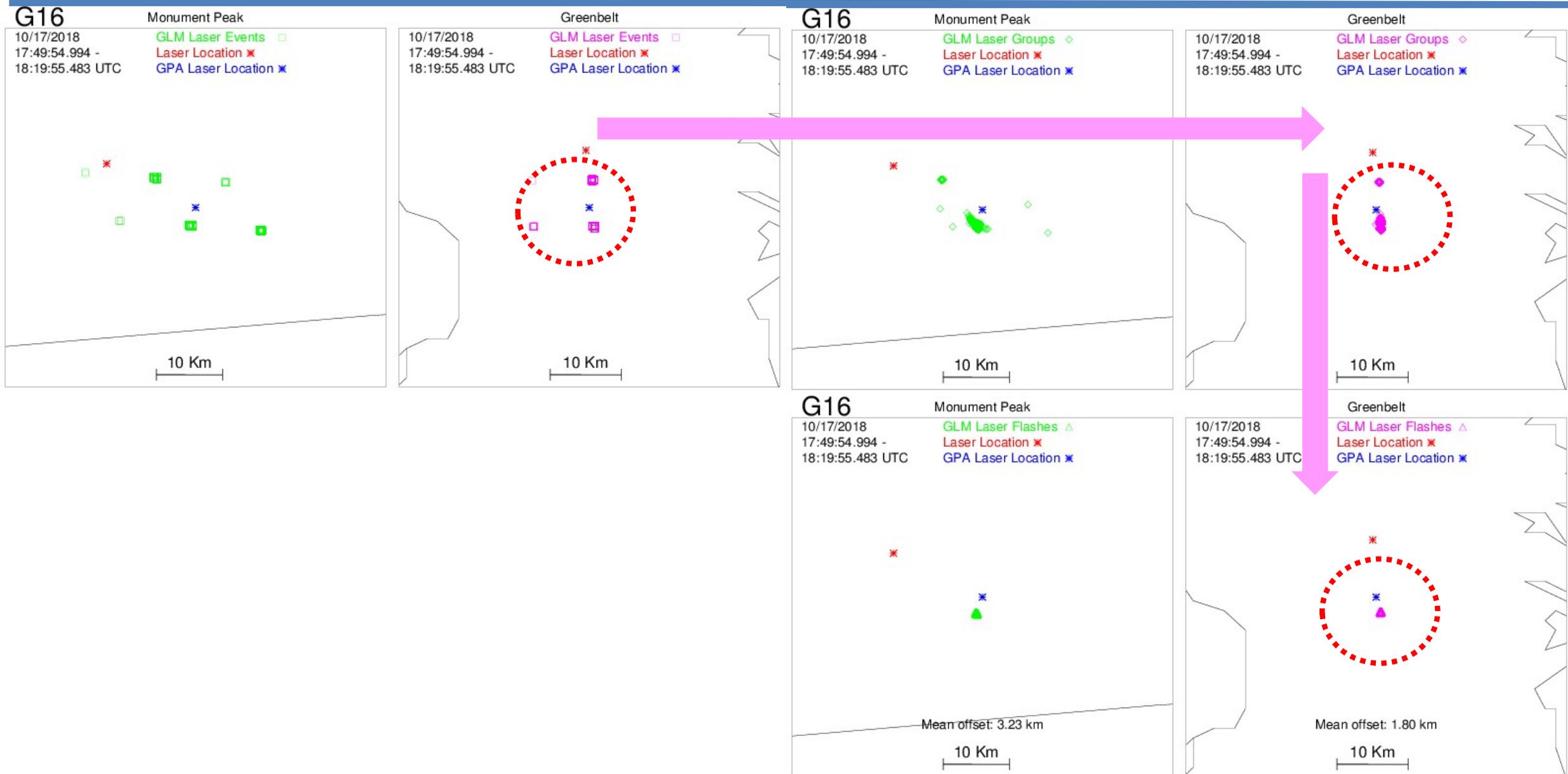
A flash is considered ended when no nearby groups occur for **1/3 s**.

**Event geolocation** - pixel latitude, longitude assuming specified cloud top height

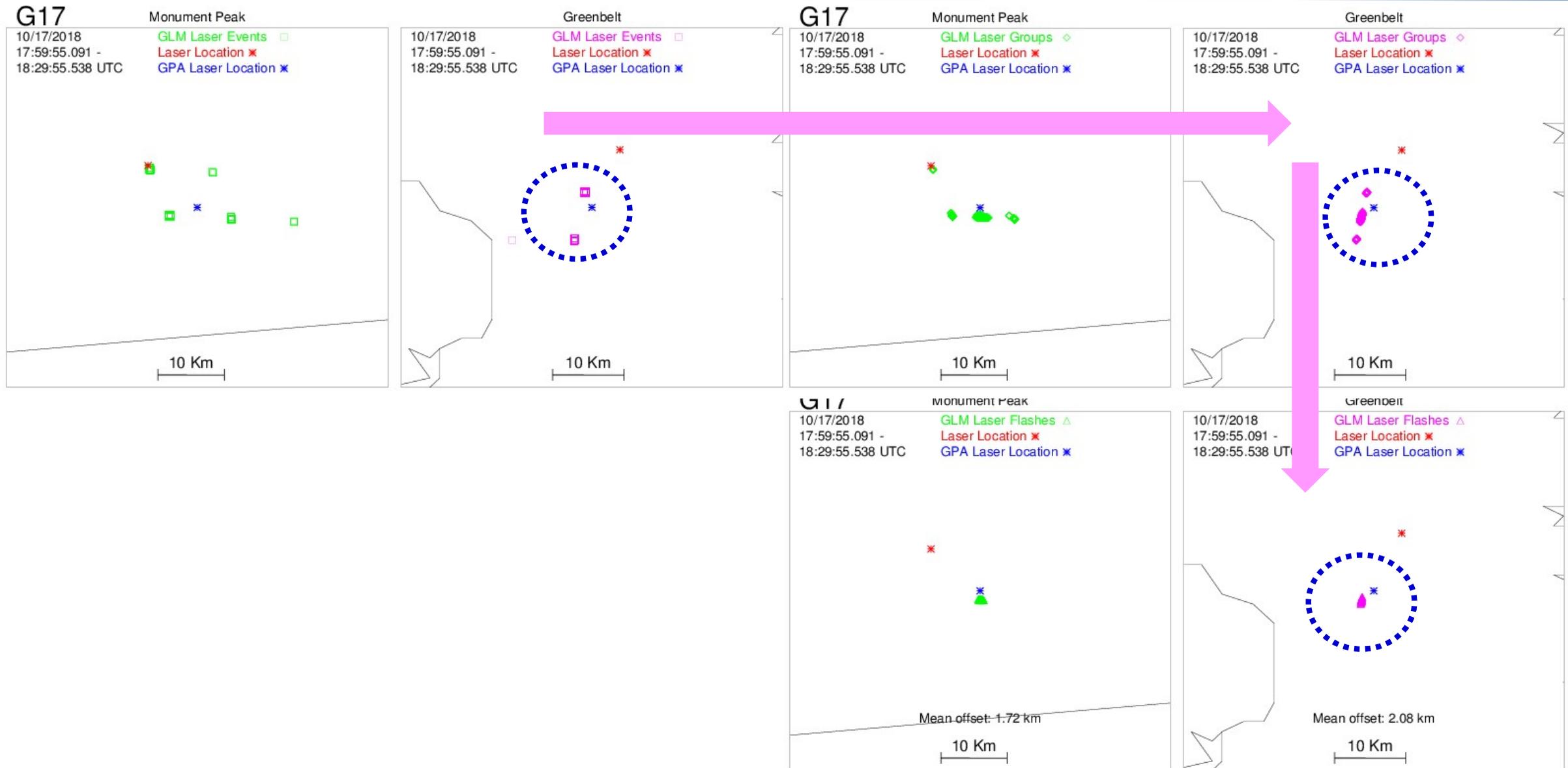
**Group geolocation** - Radiance weighted mean event location

**Flash geolocation** - Radiance weighted mean group location

# G16 - Beacon Data Analysis: Events to Groups to Flashes



# G17- Beacon Data Analysis: Events to Groups to Flashes



# Summary

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1. The laser beacons from the 2 SLR sites took GLM data during **Apr 2017- Oct 2018**.
2. SLR site coordinates provided **precise location for data translation** to the cloudtop.
3. Unlike natural lightning, the laser beacon delivers a fixed PRF, allowing **correlation of L0, L1b, and L2 time series**.
4. Data taken under varying **diurnal conditions, S/C dither, eclipse, and yaw flip**.
5. Measured values **agrees with refined preliminary models** to <2km, exceeding the 5km requirement;
6. Expects the last phase of the 2 satellite tests during the **3<sup>rd</sup>-4<sup>th</sup> week of November**