



	START TIME	END TIME	PAPER TITLE	PRESENTING AUTHOR	AFFILIATION
<b>Opening Session and Keynote Address</b>	08:30	08:45	Welcome and housekeeping	David Ball	Space Environment Research Centre, Mt Stromlo, Australia
	08:45	09:30	Contributions of SLR for the next decade	Thomas Herring	Massachusetts Institute of Technology, Cambridge, United States
<b>Session 1: SLR Contribution to Global Geodetic Observing System - A 2020 Perspective</b>	09:30	09:45	GGOS and essential geodetic variables	Richard Gross	Jet Propulsion Laboratory, Pasadena, United States
	09:45	10:00	The role of laser ranging for the Global Geodetic Observing System GGOS	Mathis Bloßfeld	Deutsches Geodätisches Forschungsinstitut - Technische Universität München, Munich, Germany
	10:00	10:30	<b>MORNING TEA</b>		
Co-Chairs: Michael Pearlman Mathis Bloßfeld Richard Gross	10:30	10:45	The synergy of Satellite Laser Ranging (SLR) and DORIS as space geodesy techniques	Frank Lemoine	NASA Goddard Space Flight Center, Greenbelt, United States
	10:45	11:00	SLR tracking of GNSS constellations - Many synergies to be explored	Daniela Thaller	Federal Agency for Cartography & Geodesy, Frankfurt am Main, Germany
<b>Finkel Theatre</b>	11:00	11:15	ILRS: Current status and future plans	Carey Noll	NASA Goddard Space Flight Center, Greenbelt, United States
	11:15	11:30	Recent progress of VGOS and its role on GGOS	Takahiro Wakasugi	Geospatial Information Authority of Japan, Tsukuba, Japan
	11:30	11:45	Extension of the SLR tracking network and its potential for the realization of Terrestrial Reference Frames	Alexander Kehm	Deutsches Geodätisches Forschungsinstitut - Technische Universität München, Munich, Germany
	11:45	12:00	The role of ground Surveys in GGOS and recent advances in ground survey techniques	Gary Johnston	Geoscience Australia
	12:00	13:30	<b>LUNCH &amp; POSTER SESSION A</b>		
<b>Session 2: Improvements in the SLR Product Quality &amp; Precise Orbit Determination</b>	13:30	13:45	Systematic error monitoring and modeling in ILRS data and products for ITRF2020 development	Vincenza Luceri	e-GEOS SpA, ASI/CGS-Matera, Matera, Italy
	13:45	14:00	Updated centre of mass correction tables for LAGEOS, Etalon, LARES, Starlette and Ajisai	José Rodríguez	BGS Space Geodesy Facility, Herstmonceux, United Kingdom
Co-Chairs: Erricos Pavlis Vincenza Luceri Krzysztof Sosnica	14:00	14:15	Estimation of the laser retro-reflector array center location for GLONASS-M	Andrey Pafnutiyev	Central Research Institute of Machine Building (TsNIIMash), Russian Federation
	14:15	14:30	Modeling revisions for improved reprocessing for ITRF2020	Erricos Pavlis	JCET, University of Maryland, Baltimore, United States
<b>Finkel Theatre</b>	14:30	14:45	Precise modeling of solar radiation pressure acceleration for spherical geodetic satellites	Akihisa Hattori	SOKENDAI (The Graduate University for Advanced Studies), Tachikawa, Japan
	14:45	15:00	VMF3o: Enhanced tropospheric mapping functions for optical frequencies	Janina Boisis	TU Wien, Vienna, Austria
	15:00	15:30	<b>AFTERNOON TEA</b>		
	15:30	15:45	Contribution of SLR observations to GNSS and LEO satellites for validating and improving LAGEOS-based parameters	Krzysztof Sońnica	Wroclaw University of Environmental and Life Sciences, Wroclaw, Polska
	15:45	16:00	Galileo precise orbit determination based on GNSS and SLR observations	Krzysztof Sońnica	Wroclaw University of Environmental and Life Sciences, Wroclaw, Polska
	16:00	16:15	The effect of SLR tracking scenarios to GNSS satellites in a combined GNSS/SLR solution	Florian Andritsch	Astronomical Institute, University of Bern, Switzerland
	16:15	16:30	Evaluating the potential of combined SLR gravity field solutions	Mathis Bloßfeld	Deutsches Geodätisches Forschungsinstitut - Technische Universität München, Munich, Germany
	16:30	16:45	SLR and GRACE gravity field determination and combination	Ulrich Meyer	Astronomical Institute, University of Bern, Switzerland
	16:45	17:00	Initial combination of our SLR weekly solutions with other Analysis Centers	Fan Shao	Shanghai Astronomical Observatory, Chinese Academy of Sciences, Shanghai, China
	17:00	19:00	 <b>WELCOME RECEPTION</b> Sponsored by the ACT Government John Curtin School of Medical Research Foyer		



	START TIME	END TIME	PAPER TITLE	PRESENTING AUTHOR	AFFILIATION	
	08:00	08:30	<b>Space Debris Study Group Meeting</b> Seminar Room 1 (refer to map on page 8) Meet in JCSMR Foyer at 07:45			
<b>Session 3: Satellite Missions &amp; Techniques for Geodetic Applications</b>  Co-Chairs: John Degnan Ulrich Schreiber Andrey Sokolov	08:30	08:45	Thermal-optical design of a geodetic satellite for one millimeter accuracy	Erricos Pavlis	JCET, University of Maryland, Baltimore, United States	
	08:45	09:00	Status of the ILRS support for the GRACE-FO mission	Sven Bauer	GeoForschungsZentrum, Potsdam, Germany	
	09:00	09:15	Tracking of GNSS satellites - Useage in the GNSS community	Thomas Schildknecht	Astronomical Institute, University of Bern, Switzerland	
	09:15	09:30	Precise orbit determination of the Ranging And Nanosatellite Guidance Experiment (RANGE)	Jake Griffiths	Naval Research Laboratory, Washington, United States	
	<b>Finkel Theatre</b>	09:30	09:45	Satellite laser ranging evaluation to Quasi-Zenith Satellite System	Ryoma Ishibashi	NEC Corporation, Fuchu, Japan
		09:45	10:00	Current status and expected performance of European Laser Timing	Ulrich Schreiber	Technical University of Munich, Germany
		10:00	10:30	<b>MORNING TEA</b>		
		10:30	10:45	Verification of ELT performance by Monte Carlo simulations	Anja Schlicht	Technical University of Munich, Germany
		10:45	11:00	Common view time transfer by diffuse reflections from space debris objects	Ulrich Schreiber	Technical University of Munich, Germany
		11:00	11:15	Laser ranging to measure LightSail orbit raising	Toshimichi Otsubo	Hitotsubashi University
	11:15	11:30	ILRS support and flight results of distributed nanosatellite mission S-NET	Peiyuan Wang	Space Research Institute, Austrian Academy of Sciences, Graz, Austria	
	11:30	11:45	Attitude determination of Galileo spacecraft using high resolution kHz SLR	Michael Steindorfer	Space Research Institute, Austrian Academy of Sciences, Graz, Austria	
	11:45	12:00	Gravity field determination using post-Newtonian energy integral	Joseph O'Leary	University of South Australia / Space Environment Research Centre, Australia	
	12:00	13:00	<b>LUNCH &amp; POSTER SESSION A</b>			
<b>Session 4: Network Operations &amp; Site Upgrades</b>	13:00	13:15	Toward high-rate on-time mm-accurate SLR at Stafford, Virginia	Jake Griffiths	U.S. Naval Research Laboratory, Washington, United States	
	13:15	13:30	Towards turnkey SLR systems: New ESA Laser Ranging Station (ELRS)	Andre Kloth	Geophysical & Geodetic Observation Systems, Potsdam, Germany	
Co-Chairs: Hyung-Chul Limm Randall Ricklefs Zhang Zhongping	13:30	13:45	Laser ranging in Main metrological center of the Russian State service of time, frequency and the Earth rotation parameters determination	Igor Blinov	National Research Institute of Technical Physics and Radio Engineering, Moscow, Russian Federation	
	13:45	14:00	Plans and study of JAXA's next SLR station	Takehiro Matsumoto	Japan Aerospace Exploration Agency, Tsukuba, Japan	
<b>Finkel Theatre</b>	14:00	14:15	EUROLAS Data Center (EDC) - recent developments (site logs, station history logs, and data transfer)	Christian Schwatke	Deutsches Geodätisches Forschungsinstitut - Technische Universität München, Munich, Germany	
	14:15	14:30	Optimization of the current SLR tracking network: potential for SLR-derived reference frames	Alexander Kehm	Deutsches Geodätisches Forschungsinstitut - Technische Universität München, Munich, Germany	
	14:30	14:45	Determination of the coordinates of SLR stations from the LARES satellite	Stanislaw Schillak	Polish Air Force Academy, Deblin, Poland	
	14:45	15:00	Official IWLR2018 delegate group photo			
	15:00	15:30	<b>AFTERNOON TEA</b>			

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## TUESDAY 6 NOVEMBER CONTINUED

<b>Session 5: Sources of Systematic Errors</b>	15:30	15:45	Monitoring the time biases in laser ranging stations thanks to the Time Transfer by Laser Link T2L2 experiment	Alexandre Belli	NASA Goddard Space Flight Center, Greenbelt, United States
	15:45	16:00	Accurate optical time transfer between a clock on ground and in space	Ulrich Schreiber	Technical University of Munich, Bad Koetzing, Germany
	16:00	16:15	Some unstable factors affecting displacement in SLR range measurements	Igor Ignatenko	National Research Institute of Technical Physics and Radio Engineering, Moscow, Russian Federation
<b>Finkel Theatre</b>	16:15	16:30	Further studies on the influence of range biases	Daniel Koenig	Federal Agency for Cartography and Geodesy, Hesse, Germany
	16:30	16:45	Systematic SLR errors detected in precise orbit determination	Toshimichi Otsubo	Hitotsubashi University, Kunitachi, Japan
	16:45	17:00	Implementing consistent clipping in the reduction of SLR data from SGF, Herstmonceux	Matthew Wilkinson	NERC Space Geodesy Facility, Herstmonceux, United Kingdom
	17:00	17:15	Processing of SLR observations with an optimal Wiener filter - an alternative way to calculate normal points	Stefan Riepl	Federal Agency for Cartography and Geodesy, Bad Kötzing, Germany
	17:15	17:30	A data processing approach to high precision, high return rate kHz SLR stations	John Degnan	Sigma Space Corp, Lanham, United States
17:30	18:30	<b>Missions Standing Committee Meeting</b> Seminar Room 1			
18:30	19:00	<b>Networks and Engineering Standing Committee Meeting</b> Seminar Room 1			

## Wednesday 7 November



**The John Curtin School of Medical Research**  
131 Garran Rd, Acton  
Workshop location

	START TIME	END TIME	PAPER TITLE	PRESENTING AUTHOR	AFFILIATION
<b>Session 6: Characteristics of Retroreflector Arrays</b>	08:30	08:45	Thermal-optical performance of the GPS III Laser Retroreflector Array	Stephen Merkowitz	NASA Goddard Space Flight Center, Greenbelt, United States
	08:45	09:00	Characterization of the optical performance of COTS laser retroreflectors for ASI-INFN Joint Projects	Chiara Mondaini	Istituto Nazionale di Fisica Nucleare, Frascati (Rome), Italy
Co-Chairs: Simone Dell'Agnello José Rodríguez Linda Thomas	09:00	09:15	kHz SLR application on the attitude analysis of Technosat	Peiyuan Wang	Space Research Institute Austrian Academy of Sciences, Graz, Austria
<b>Finkel Theatre</b>	09:15	09:30	Microreflectors for Mars, Phobos/Deimos and Asteroids/Comets	Marco Muccino	Istituto Nazionale di Fisica Nucleare, Frascati (Rome), Italy
	09:30	09:45	Experimental determination of photometric characteristics of the BLITS-M satellite and its range correction	Vyacheslav Murashkin	Research-and-Production Corporation Precision Systems and Instruments, Moscow, Russian Federation
	09:45	10:00	Retroreflector systems to determine the coordinates of SC moving parts	Andrey Sokolov	Research-and-Production Corporation Precision Systems and Instruments, Moscow, Russian Federation
	10:00	10:30	<b>MORNING TEA</b>		
<b>Session 7: Developments in Software &amp; Automation</b>	10:30	10:45	Use of a night-tracking camera for real time correction of the pointing of the SLR system	Emiliano Cordelli	Astronomical Institute University of Bern, Switzerland
	10:45	11:00	The status of WLRs system automation	Johann Eckl	Federal Agency for Cartography and Geodesy, Bad Kötzing, Germany
Co-Chairs: Chris Moore Pierre Lauber Evan Hoffman	11:00	11:15	Sequential processing of ILRS observations - Experiences over the last 5 years	David Vallado	Center for Space Standards and Innovation, AGI, Colorado, United States
<b>Finkel Theatre</b>	11:15	11:30	Development of automated SLR data processing at Mount Stromlo SLR Station	Christopher Moore	EOS Space Systems, Australia
	11:30	11:45	Updates to the ILRS predictions and data formats	Randall Ricklefs	Center for Space Research, University of Texas at Austin, Austin, United States
	11:45	12:00	Station assessment software - Overview	Justine Woo	Sigma Space Corp, Lanham / National Aeronautics and Space Administration, Greenbelt, United States
	12:00	13:30	<b>LUNCH &amp; POSTER SESSION B</b>		

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Clinic Sessions	13:30	14:10	<b>1: Data Quality</b> Erricos Pavlis, Krzysztof Sośnica	<b>2: Data Productivity</b> Randall Carman, Robert Sherwood	<b>3: System Accuracy / Biases</b> Toshimichi Otsubo, José Rodríguez	<b>4: ILRS Procedures</b> Randall Ricklefs, Christian Schwatke	<b>5: Web Tools and Software</b> Matthew Wilkinson, Michael Steindorfer	<b>6: Calibration and Ground Targets</b> Georg Kirchner, Ulrich Schreiber
	14:20	15:00						
			<b>Finkel Theatre</b>	<b>Link Room</b>	<b>Science Forum</b>	<b>Boardroom</b>	<b>Seminar Room 1</b>	<b>Seminar Room 2</b>
	15:00	15:30	<b>AFTERNOON TEA</b>					
	15:30	16:10	<b>1: Data Quality</b> Erricos Pavlis, Krzysztof Sośnica	<b>2: Data Productivity</b> Randall Carman, Robert Sherwood	<b>3: System Accuracy / Biases</b> Toshimichi Otsubo, José Rodríguez	<b>4: ILRS Procedures</b> Randall Ricklefs, Christian Schwatke	<b>5: Web Tools and Software</b> Matthew Wilkinson, Michael Steindorfer	<b>6: Calibration and Ground Targets</b> Georg Kirchner, Ulrich Schreiber
	16:20	17:00						
			<b>Finkel Theatre</b>	<b>Link Room</b>	<b>Science Forum</b>	<b>Boardroom</b>	<b>Seminar Room 1</b>	<b>Seminar Room 2</b>
	17:00	18:30	<b>Data Formats and Procedures Standing Meeting</b> Seminar Room 1					
	18:30	19:00	<b>Transponders Standing Committee Meeting</b> Seminar Room 1					
	19:00	22:00	<b>BANQUET</b> National Arboretum Buses will depart from the front steps of the JCSMR and also Edinburgh Avenue bus stop at 18:40 (see page 7 for more details)					

# Thursday 8 November



**The John Curtin School of Medical Research**  
131 Garran Rd, Acton  
Workshop location

	END TIME		PAPER TITLE	PRESENTING AUTHOR	AFFILIATION
<b>Session 8: Developments in SLR Techniques &amp; Technologies</b>	08:30	08:45	A high power laser ranging facility at JPL's TMO	Michael Shao	Jet Propulsion Laboratory, Pasadena, United States
	08:45	09:00	Concept for a new minimal SLR system	Daniel Hampf	German Aerospace Center, Stuttgart, Germany
Co-Chairs: Georg Kirchner Manuel Catalán Daniel Hampf	09:00	09:15	Development progress on NASA's Space Geodesy Satellite Laser Ranging System	Evan Hoffman	NASA Goddard Space Flight Center, Greenbelt, United States
	09:15	09:30	Modernization of Event Timer RTS 2006	Kalvis Salmins	Institute of Astronomy, University of Latvia, Riga, Latvia
<b>Finkel Theatre</b>	09:30	09:45	Near Simultaneous on-orbit Testing of GOES-16 and GOES-17 GLM payloads from 2 NASA SLR sites using collocated GLM laser beacons	Thomas Varghese	NASA SLR program and Cybioms Corporation, United States
	09:45	10:00	Progress of space qualification of the NPET Timing System for SLR and time transfer applications	Johan Westin	Czech Technical University, Prague, Czech Republic / Delft University of Technology, Delft, The Netherlands
	10:00	10:30	<b>MORNING TEA</b>		
	10:30	10:45	Reduction of atmospheric modelling errors using multiple wavelength ranging	Ben Greene	EOS Space Systems, Australia
	10:45	11:00	Space debris laser ranging test based on 1064nm laser wavelength	Dongsheng Zhai	Yunnan Observatories, Chinese Academy of Sciences, Kunming, China
	11:00	11:15	The results of full-scale tests of the new Russian laser station «Tochka»	Sergey Martynov	Research-and-Production Corporation Precision Systems and Instruments, Moscow, Russian Federation
	11:15	11:30	The Semiconductor Guidestar Laser: A novel, affordable, low SWaP sodium guide star laser for adaptive optics tracking of space objects	Celine d'Orgeville	Australian National University / Space Environment Research Centre, Canberra, Australia
	11:30	11:45	Airborne and spaceborne single photon 3D imaging Lidars	John Degnan	Sigma Space Corp, Lanham, United States
	11:45	12:00	Communications and ranging experiment using laser terminal on satellite	Hiroo Kunimori	National Institute of Information and Communications Technology, Tokyo, Japan
	12:00	13:30	<b>LUNCH &amp; POSTER SESSION B</b>		

## THURSDAY 8 NOVEMBER CONTINUED

<b>Session 9: Lunar Laser Ranging &amp; Deep Space Missions</b>  Co-Chairs: Tom Murphy Jean-Marie Torre Sven Bauer  <b>Finkel Theatre</b>	13:30	13:45	Observations from the low LEO orbit up to the moon	Johann Eckl	Federal Agency for Cartography and Geodesy, Bad Kötzing, Germany,
	13:45	14:00	Development on lunar laser ranging at Yunnan Observatories	Yaoheng Xiong	Yunnan Observatories, Chinese Academy of Sciences, Kunming, China
	14:00	14:15	Development of hollow corner cube retroreflector for the future lunar and deep space satellite laser ranging	Yun He	Sun Yat-sen University, Zhuhai, China
	14:15	14:30	Testing and physics analysis of old (Lunokhod) and new (MoonLIGHT) lunar laser retroreflectors	Luca Porcelli	Istituto Nazionale di Fisica Nucleare, Frascati (Rome) / Unical, Cosenza, Italy
	14:30	14:45	Sub-millimeter lunar laser ranging: Novel approach to Moon reference frame	Vladimir Zharov	National Research Institute of Technical Physics and Radio Engineering, Moscow, Russian Federation
	14:45	15:00	Advanced lunar laser ranging for high-precision science investigations	Slava Turyshev	Jet Propulsion Laboratory, Pasadena, United States
	15:00	15:30	<b>AFTERNOON TEA</b>		
Co-Chairs: Michael Pearlman Erricos Pavlis Giuseppe Blanco  <b>Finkel Theatre</b>	15:30	17:00	<b>Wrap-up &amp; Close</b>		
	17:00	19:00	<b>ILRS Governing Board Meeting (invitation only)</b> Seminar Room 1		

## Friday 9 November

### INTERNATIONAL WORKSHOP ON SPACE DEBRIS MANAGEMENT AND MITIGATION



**The John Curtin School of Medical Research**  
 131 Garran Rd, Acton  
 Workshop location

	START TIME	END TIME	PAPER TITLE	PRESENTING AUTHOR	AFFILIATION
<b>Opening Session and Keynote Address</b>	08:25	08:30	Welcome and housekeeping	David Ball	Space Environment Research Centre, Mt Stromlo, Australia
	08:30	09:00	Keynote Address	Moriba Jah	University of Texas at Austin and SERC International Research Management Committee
<b>Session 1: Sensors &amp; Satellite Tracking</b>  Co-Chairs: Michael Pearlman Erricos Pavlis Giuseppe Blanco  <b>Finkel Theatre</b>	09:00	09:15	SERC Research Program 1 Review: Remote manoeuvre of space debris using photon pressure for active collision avoidance	Craig Smith	EOS Space Systems, Australia
	09:15	09:30	Adaptive optics corrected imaging for satellite and debris characterisation	Michael Copeland	Australian National University / Space Environment Research Centre, Canberra, Australia
	09:30	09:45	Tracking non-cooperative low earth orbit objects using GNSS satellites as a multi-static radar	Sohrab Mahmud	University of New South Wales, Campbell, Australia
	09:45	10:00	Photon counting detector for both passive and active space debris optical tracking	Georg Kirchner	Austrian Academy of Sciences, Graz - Lustbuehel, Austria
	10:00	10:15	Mission characterization of LEO targets	Pawel Lejba	Space Research Centre of the Polish Academy of Sciences, Kornik, Poland
	10:15	10:30	Multi-kW high beam quality CW laser for space debris manoeuvring	Yue Gao	EOS Space Systems, Australia
	10:30	11:00	<b>MORNING TEA</b>		
<b>Session 2: Orbit Determination &amp; Propagation Session</b>  Co-Chairs: Moriba Jah Michael Steindorfer Igor Zayer  <b>Finkel Theatre</b>	11:00	11:15	Overview and research findings of SERC Research Program 2: Orbit Determination and Predicting Behaviours of Space Objects	Robert Norman	RMIT University, Australia; SERC Limited, Australia,
	11:15	11:30	Local orbit uncertainty reduction in follow-up passes based on single-pass debris laser ranging	Christoph Bamann	Technical University of Munich, Germany
	11:30	11:45	Real time improvement of orbits of space debris by fusing SLR and astrometric data acquired by a night-tracking camera	Emiliano Cordelli	Astronomical Institute University of Bern (AIUB), Bern, Switzerland
	11:45	12:00	Orbit determination for space debris tracking using laser ranging and angular data from an encoder in Geochang SLR system	Simon Kim	Korea Astronomy and Space Science Institute, South Korea
	12:00	12:15	Orbit determination and prediction accuracy of TOPEX with a priori solar radiation force derived from photometrics and laser ranging data	Michael Lachut	EOS Space Systems, Queanbeyan / Space Environment Research Centre, Mt Stromlo, Australia
	12:15	12:30	Coupled orbit-attitude evolution estimation enhancement using machine learning	Rasit Abay	UNSW Canberra, Australia

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**FRIDAY 9 NOVEMBER CONTINUED**

	12:30	12:45	Official IWLR2018 delegate group photo		
	12:45	13:30	<b>LUNCH &amp; SPACE DEBRIS POSTER SESSION</b>		
<b>Session 3: Conjunction Analysis &amp; Collision Avoidance Session</b>  Co-Chairs: James Bennett Daniel Kucharski Quirin Funke  <b>Finkel Theatre</b>	13:30	13:45	A new Australian conjunction assessment and threat warning service	James Bennett	Space Environment Research Centre, Mount Stromlo, Australia
	13:45	14:00	Operational collision avoidance at ESOC	Quirin Funke	IMS @ European Space Agency, Darmstadt, Germany
	14:00	14:15	Enhancement software package for collision risk mitigation in KARI	Jaedong Seong	Korea Aerospace Research Institute, Daejeon, South Korea
	14:15	14:30	Assessing GEO close encounter warnings for spacecraft operations	Sven Flegel	Space Environment Research Centre, Canberra / Visiting Researcher to the Royal Melbourne Institute of Technology, Australia
	14:30	14:45	Informative optimal collision avoidance manoeuvres using deep learning	Rasit Abay	UNSW Canberra, Australia
	14:45	15:00	Laser Precision Collision Avoidance: A new concept in space debris mitigation	Toshikazu Ebisuzaki	IZEST/Ecole Polytechnique, Paris, France
	15:00	15:30	<b>AFTERNOON TEA</b>		
<b>Session 4: Mitigation &amp; Remediation Session</b>  Co-Chairs: Ben Greene Matthew Bold Jung Hyun  <b>Finkel Theatre</b>	15:30	15:45	Space Environment Research Centre: Space segment overview	Benjamin Sheard	Space Environment Research Centre, Mt Stromlo, Australia; EOS Space Systems, Australia
	15:45	16:00	A systematic study of laser ablation for space debris mitigation	Francesco Nozzoli	Trento Institute for Fundamental Physics and Applications-National Institute for Nuclear Physics, Trento, Italy
	16:00	16:15	Deorbiting mission of cm-sized space debris by laser ablation	Toshikazu Ebisuzaki	Riken, Wako, Japan
	16:15	16:30	High-definition Photometry - New tool for space debris characterization	Daniel Kucharski	Space Environment Research Centre, Canberra, Australia / The University of Texas, Austin, USA,
	16:30	16:45	Investigation into the rotational dynamics of the defunct satellite TOPEX/Poseidon	Luc Sagnières	McGill University, Montreal, Canada / IMCCE, Observatoire de Paris, France
	16:45	17:00	Collision avoidance using ground based lasers	Liam Smith	Lockheed Martin, Colorado, United States
	17:00	17:30	<b>Closing session &amp; keynote:</b> Ben Greene, Electro Optic Systems, Australia		
	18:00	21:00	<b>EOS Space Research Centre Telescope Tour &amp; BBQ</b> Sponsored by SERC Mount Stromlo Observatory Buses will depart from the front steps of the JCSMR at 17:40 (See page 7 for more details)		

SESSION	POSTER NUMBER	PAPER TITLE	PRESENTING AUTHOR	AFFILIATION
<b>Session 1. SLR Contribution to Global Geodetic Observing System - A 2020 Perspective</b>	A1	NASA CDDIS: Important changes to user access	Carey Noll	NASA Goddard Space Flight Center, Greenbelt, United States
	A2	New horizons for Latin American SLR network	Pablo Raul Yanyachi	Universidad Nacional de San Agustín de Arequipa, Peru
<b>Session 2. Improvements in the SLR Product Quality &amp; Precise Orbit Determination</b>	A3	A combined solution of SLR, SLR to GNSS and GNSS at Normal Equations Level: Preliminary results and facts	Dimitrios Ampatzidis	Federal Agency for Cartography and Geodesy, Hessen, Germany
	A4	Expanded SLR target constellation for improved future ITRFs	Erricos Pavlis	JCET, University of Maryland, Baltimore, United States
	A5	Network effects and handling of geocentre motion in SLR and GNSS solutions	Krzysztof Sośnica	University of Environmental and Life Sciences, Wrocław, Poland
	A6	A common mode error explore for GNSS/VLBI/SLR/DORIS based on PCA method	Xiaoya Wang	Shanghai Astronomical Observatory, Chinese Academy of Science, China
	A7	A new model of the mean albedo of the earth: Estimation and validation from the GRACE mission and SLR satellites	Florent Deleflie	IMCCE, Observatoire de Paris, France
<b>Session 3. Satellite Missions &amp; Techniques for Geodetic Applications</b>	A8	Status of the GRGS analysis center	Florent Deleflie	IMCCE, Observatoire de Paris, France
	A9	Role of laser measurements in the Geo-IK-2 mission	Natalia Parkhomenko	Research-and-Production Corporation Precision Systems and Instruments, Moscow, Russian Federation
	A10	Station performance of the Sazhen-TM system at Hartebeesthoek	Roelf Botha	Hartebeesthoek Site, SARAQ, Krugersdorp, South Africa
	A11	Status and recent upgrades at MOB LAS5/Yarragadee	Randall Carman	Geoscience Australia, Canberra, Australia
	A12	San Fernando laser station latest upgrades and news	Manuel Catalán	Royal Observatory of the Spanish Navy, Spain
	A13	The improvement on data quality of Changchun High Repetition Rate Laser Ranging System	Xue Dong	Changchun Observatory, Chinese Academy of Sciences, Changchun, China
	A14	Stuttgart SLR stations	Daniel Hampf	German Aerospace Center, Stuttgart, Germany
	A15	Syowa Geodetic Station in Antarctica: Current status and future prospects	Akihisa Hattori	SOKENDAI (The Graduate University for Advanced Studies), Tachikawa, Japan
	A16	Status of the NASA SGSLR Gimbal and telescope assembly build and test	Julie Horvath	Kbrwyle Technology Solutions, Lanham, United States
	A17	The state and development of laser ranging measurements at the Mendeleev SLR station	Igor Ignatenko	National Research Institute of Technical Physics and Radio Engineering, Moscow, Russian Federation
	A18	Satellite laser ranging at station 1893 (Katzively) in 2017	Igor Ignatenko	National Research Institute of Technical Physics and Radio Engineering, Moscow, Russian Federation
	A19	The state and development of laser ranging measurements at the Irkutsk SLR station	Igor Ignatenko	National Research Institute of Technical Physics and Radio Engineering, Moscow, Russian Federation
	A20	Need for a Space Geodetic Station around Indian Ocean Region	Elango Kattimuthu	Indian Space Research Organisation, Karnataka, India
	A21	Current NASA SLR network operations	Rivers Lamb	NASA Goddard Space Flight Center, Greenbelt, United States
	A22	Kunming Station New Satellite Laser Ranging System	Zhulian Li	Yunnan Observatories, Chinese Academy of Sciences, Kunming, China

SESSION	POSTER NUMBER	PAPER TITLE	PRESENTING AUTHOR	AFFILIATION
<b>Session 4. Network Operations &amp; Site Upgrades</b>	A23	Past (LURE), present (TLRS-4) and future (SGSLR) of laser ranging at Haleakala, Maui	Daniel O'Gara	University of Hawaii Institute for Astronomy, United States
	A24	Metsähovi Geodetic Research Station - a future GGOS core station	Arttu Raja-Halli	Finnish Geospatial Research Institute, Uusimaa, Finland
	A25	The McDonald Geodetic Observatory (MGO)	Randall Ricklefs	Center for Space Research, The University of Texas at Austin, United States
	A26	Tanegashima Station (GMSL) status report	Takushi Sakamoto	Japan Aerospace Exploration Agency, Tsukuba, Japan
	A27	SLR Station Riga status report	Kalvis Salmins	University of Latvia Institute of Astronomy, Riga, Latvia
	A28	Coordinates of the Borowiec SLR station in 2015-2018	Stanislaw Schillak	Polish Air Force Academy, Deblin, Poland
	A29	EUROLAS Data Center (EDC) - Status Report 2016-2018	Christian Schwatke	Deutsches Geodätisches Forschungsinstitut - Technische Universität München, Munich, Germany
	A30	Latest activities and developments at the SGF, Herstmonceux	Matthew Wilkinson	NERC Space Geodesy Facility, Herstmonceux, United Kingdom

# POSTER SESSION B

Wednesday 7 November and Thursday 8 November 2018  
(during lunch)

SESSION	POSTER NUMBER	PAPER TITLE	PRESENTING AUTHOR	AFFILIATION
<b>Session 4. Network Operations &amp; Site Upgrades</b>	B1	NASA Network sustainment analysis & trends	Christopher Szwec Kate Stevenson Rivers Lamb	Peraton / NASA, Greenbelt, United States
	B2	Status of the establishment of the Yebes Laser Ranging Station (YLARA)	Beatriz Vaquero-Jiménez José Manuel Serna-Puente	Yebes Observatory (IGN-Spain), Spain
	B3	Station assessment software - Initial results	Justine Woo Evan Hoffman	Sigma Space Corp, Lanham, United States
	B4	Installation of GNSS receivers and laser reflector in volcanoes and hills surrounding the Arequipa Station	Pablo Raul Yanyachi	Universidad Nacional de San Agustín de Arequipa, Peru
	B5	Development of transportable cabin-based SLR system with 60cm aperture telescope	ZhongPing Zhang	Shanghai Astronomical Observatory, Chinese Academy of Science, China
<b>Session 5. Sources of Systematic Errors</b>	B6	Analyzing prediction quality with the Potsdam Time Bias Service	Sven Bauer	GeoForschungsZentrum, Potsdam, Germany
	B7	Extended troposphere delay model dedicated for Satellite Laser Ranging	Mateusz Drozdowski	University of Environmental and Life Sciences, Wroclaw, Poland
	B8	JCET web tools for the assessment of the ILRS Network's performance	Erricos Pavlis	JCET, University of Maryland, Baltimore, United States
<b>Session 6. Characteristics of Retroreflector Arrays</b>	B9	Development of reflectors for motion grasp of space debris	Takehiro Matsumoto	Japan Aerospace Exploration Agency, Tsukuba-city, Japan

**POSTER SESSION B CONTINUED**

SESSION	POSTER NUMBER	PAPER TITLE	PRESENTING AUTHOR	AFFILIATION
<b>Session 7. Developments in Software &amp; Automation</b>	B10	ELT data filtering in presence of multiple laser retro-reflectors	Christoph Bamann	Technical University of Munich, Germany
	B11	SLR analysis with the DGFI-TUM software DOGS-OC/-CS	Mathis Bloßfeld	Deutsches Geodätisches Forschungsinstitut - Technische Universität München, Munich, Germany
	B12	Updates on ESA tools supporting debris laser ranging	Quirin Funke	IMS @ European Space Agency, Darmstadt, Germany
	B13	Implements of cpf and crd algorithm in Python	Rongwang Li	Yunnan Observatories, Chinese Academy of Sciences, Kunming, China
	B14	Multi-technique capabilities in GipsyX	Paul Ries	Jet Propulsion Lab, Pasadena, United States
	B15	Raspberry Pi based temperature monitoring network at the SLR station Riga 1884	Kalvis Salmins	University of Latvia Institute of Astronomy, Riga, Latvia
	B16	Software control system upgrade at Stafford, Virginia	Walter Reed Smith	Naval Research Laboratory, Washington, United States
	B17	ILRS operation centers CRD quality check upgrade	Kate Stevenson	Peraton, Greenbelt, United States
	B18	Quick analysis using orbitNP.py of full-rate SLR data submitted to the ILRS in 2018	Matthew Wilkinson	NERC Space Geodesy Facility, Herstmonceux, United Kingdom
	B19	Aircraft detection using a digital camera aligned to the SLR laser at the SGF, Herstmonceux	Matthew Wilkinson	NERC Space Geodesy Facility, Herstmonceux, United Kingdom
	B20	Software best practices at Crustal Dynamics Data Information System (CDDIS): Steps to consider	Justine Woo	Sigma Space Corp, Lanham, United States
<b>Session 8. Developments in SLR Techniques &amp; Technologies</b>	B21	The NASA SGSLR approach to range gate and laser fire control	Christopher Clarke	KBRwyle Technology Solutions, Lanham, United States
	B22	100 kHz satellite laser ranging demonstration at MLRO	Daniele Dequal	Agenzia Spaziale Italia, Italy
	B23	Introduction to reliable SLR In-Sky-Safety methods in operation at the GGOS Site Wettzell	Johann Eckl	Federal Agency for Cartography and Geodesy, Bad Kötzing, Germany
	B24	Laser activity of the Borowiec laser station in years 2017-2018	Pawel Lejba	Space Research Centre Polish Academy of Sciences, Warsaw, Poland
	B25	Coherent Optical Doppler Orbitography	Sascha Schediwy	ICRAR / University of Western Australia, Australia
	B26	SLR station Graz: Station overview and current status	Michael Steindorfer	Space Research Institute, Austrian Academy of Sciences, Graz, Austria
	B27	Time synchronization for Bi-static laser ranging via fiber-based time and frequency transfer	Haifeng Zhang	Shanghai Astronomical Observatory, Chinese Academy of Science, China
	B28	Preliminary test results of the new 1m Aperture SLR telescope in Wuhan National Geodetic Observatory	Jie Zhang	Institute of Geodesy and Geophysics, Chinese Academy of Sciences, Wuhan, China
	B29	Method for comparing time scales: Accuracy estimates and necessary corrections	Igor Ignatenko	National Research Institute for Physical-Technical and Radio Engineering Measurements, Mendeleevo, Russian Federation
<b>Session 9. Lunar Laser Ranging &amp; Deep Space Missions</b>	B30	Processing and analysis of lunar laser ranging observations in Crimea in 1974-1984	Igor Ignatenko	National Research Institute of Technical Physics and Radio Engineering, Moscow, Russian Federation
	B31	Calibration, gravity signals, and model uncertainties relating to the Apache Point Observatory Lunar Laser-ranging Operation (APOLLO)	Ulrich Schreiber	Technical University of Munich, Germany

# SPACE DEBRIS POSTER SESSION

Friday 9 November  
(during lunch)

SESSION	POSTER NUMBER	PAPER TITLE	PRESENTING AUTHOR	AFFILIATION
<b>Session 1: Sensors &amp; Satellite Tracking</b>	SD1	Changchun Tiangong-1 Space debris joint observation	Xue Dong	Changchun Observatory, Chinese Academy of Sciences, Changchun, China
	SD2	The Semiconductor Guidestar Laser: A novel, affordable, low SWaP sodium guide star laser for adaptive optics tracking of space objects	Celine d'Orgeville	Australian National University / Space Environment Research Centre, Canberra, Australia
	SD3	Data validation and fault diagnosis of APOSOS telescope using satellite laser ranging data	Pengqi Gao	National Astronomical Observatories, Chinese Academy of Sciences, Beijing, China
	SD4	A summary of Graz Light curves measurements since 2015	Peiyuan Wang	Space Research Institute Austrian Academy of Sciences, Styria, Austria
	SD5	Development and architecture of the EOS Guide Star Laser	James Webb	EOS Space Systems, Queanbeyan, Australia
<b>Session 2: Orbit Determination &amp; Propagation Session</b>	SD6	Using SLR observations of Low Earth Orbiting satellites to scale neutral thermospheric density	Mathis Bloßfeld	Deutsches Geodätisches Forschungsinstitut - Technische Universität München, Munich, Germany
	SD7	Search and track multi-sensor multi-target tracking for orbit determination and catalog maintenance of geosynchronous space objects	Han Cai	RMIT University, Melbourne / Space Environment Research Centre, Mt Stromlo, Australia
	SD8	Benefits from the first deployment of the Expert Centre for supporting laser-ranging observations: Status report and possible implications on orbit improvement	Quirin Funke	IMS @ European Space Agency, Darmstadt, Germany
	SD9	Accelerometer-derived thermosphere density from Swarm-C and advancements in physics-based modelling	Robert Norman	RMIT University, Melbourne / Space Environment Research Centre, Mt Stromlo, Australia
	SD10	Multiple space objects tracking and orbit determination considering uncertain parameters	Yang Yang	RMIT University, Melbourne / Space Environment Research Centre, Mt Stromlo, Australia
<b>Session 3: Conjunction Analysis &amp; Collision Avoidance Session</b>	SD11	Design of a high-performance conjunction assessment service	Marek Moeckel	Space Environment Research Centre, Mt Stromlo, Australia
	SD12	Increasing the determinacy and uniqueness of solutions to the physical characteristics and non-natural behaviours of near-earth orbiting space objects	Richard Samuel	Space Environment Research Centre / Australian National University, Weston Creek, Australia
	SD13	Design & development of an optimized sensor scheduling & tasking programme for tracking space objects	David Shteinman	Industrial Sciences Group, Sydney, Australia
<b>Session 4: Mitigation &amp; Remediation Session</b>	SD14	Removal of small-sized space debris by laser-ablative momentum generation	Daniel Hampf	German Aerospace Center, Stuttgart, Germany
	SD15	SLR observation of Tiangong-1 for its rotational state	You-yuan Lin	Purple Mountain Observatory, Nanjing, China