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POD improvements of GNSS satellites
through the measurements of their non-
gravitational accelerations by means of an
onboard accelerometer

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Summary

1. Motivations
2. Order-of-magnitude of the perturbing accelerations on GALILEO2-sat
3. Accelerometer: measurements and physical characteristics
4. Simplified model for a GALILEO2-sat and for its orbit
5. Simulations for SRP and Albedo effects
6. Preliminary results in terms of accelerometer performance
7. Conclusions

Motivations

- The solar radiation pressure (**SRP**) represents the largest non-gravitational perturbation (**NGP**) acting on the orbit of a spacecraft of the **GNSS**
- **NGPs** are in general difficult to model, also for spherical in shape satellites, much more for complex in shape satellites such as those of the **GPS**, **GLONASS**, **BEIDOU** ... and **GALILEO** constellations
- Eclipses and orbit maneuvers represent additional complications for a refined modelling

Consequently:

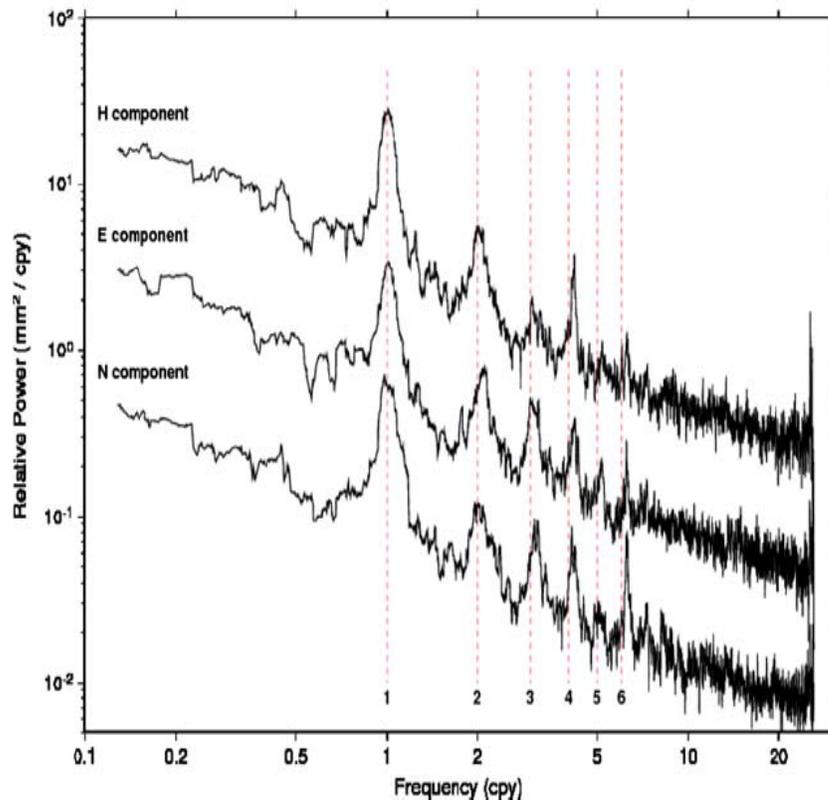
- **Current precise orbit determination (POD) of GNSS satellites is not so precise as desired**
- **Systematic errors found in the orbits of GNSS satellites, as well as in the derived geodetic parameters, show that significant NGPs mis-modelling is still present, as for SRP, thermal effects, ...**

Motivations

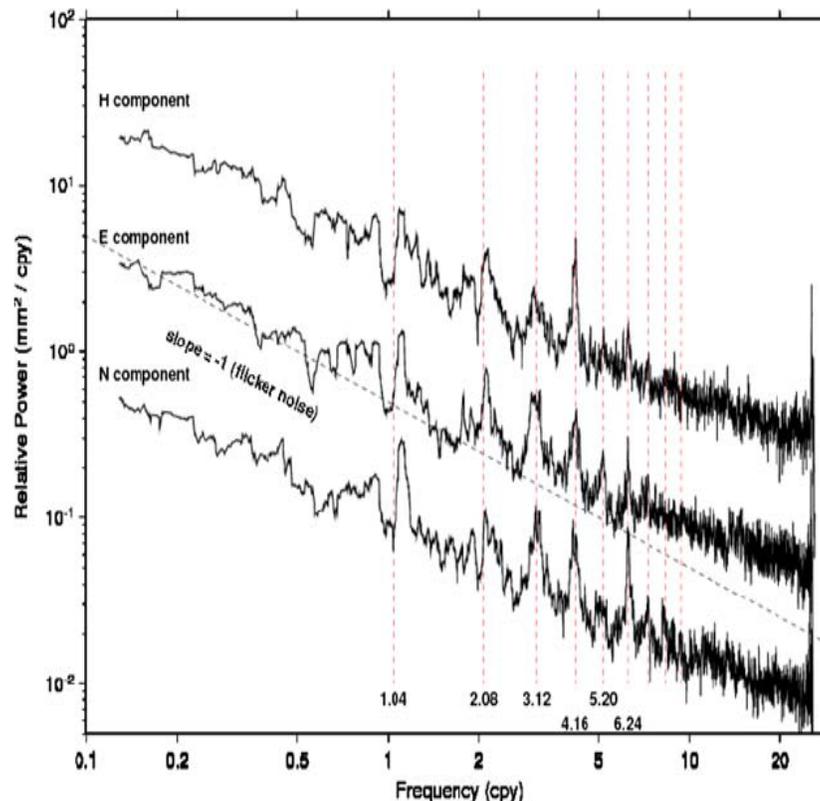
Evidence for 1.04 cpy and higher harmonics in the stacked (167 stations) and filtered spectra of non-linear position residuals of the weekly IGS stations solutions included in ITRF2005 (Ray et al, GPS Solut **12** (2008)).

This frequency is very close to that of the Draconit-year (1.039 cpy) ...

Spectra for Unfiltered GPS Time Series



Spectra for Filtered GPS Time Series



The fundamental harmonic @ 1.040 ± 0.008 cpy and its close relation with the Draconitic year could indicate:

- **Systematic errors related with satellites orbit mismodelling also in relationship with the complex Sun-satellite interactions**
- **Aliasing of site-dependent positioning biases**

Motivations

As consequence of the above main points and also to improve the final precision of the **GALILEO** user-segment, the European Space Agency (**ESA**) because of its efforts to provide a **new constellation of GNSS**, and especially in view of **next generation of GALILEO**, beside being interested in possible **improvements of the NGPs models** is also envisaging **to use an onboard accelerometer** to directly measure the **non-gravitational accelerations** and finally **improve the POD** of each spacecraft of the **GALILEO constellation**

The **Experimental Gravitation** group of **IAPS/INAF** has a long experience in developing sensors for **geophysics** and **fundamental physics** measurements

Order-of-magnitude of the perturbing accelerations on GALILEO2-sat

Gravitational and non gravitational perturbations: amplitude of the acceleration and orbital effects over 1-day

Acceleration term	Formula	GALILEO2 [m/s ²]	R [m]	T [m]	W [m]
Main gravitational accelerations					
Earth's monopole	GM_{\oplus}/r^2	0.45	∞	∞	∞
Earth's oblateness	$3(GM_{\oplus}/r^2)(R_{\oplus}/r)^2 J_{20}$	3.1×10^{-5}	1780	20713	9709
Low order geopotential	$3(GM_{\oplus}/r^2)(R_{\oplus}/r)^2 J_{22}$	1.8×10^{-7}	10	120	56
Moon	$2(GM_m/r_m^3)r$	5.1×10^{-6}	446	2007	33
Sun	$2(GM_{\odot}/r_{\odot}^3)r$	2.3×10^{-6}	223	1338	446
Earth's tides	$3k_2(GM_m/r_m)(R_{\oplus}/r_m)^2(R_{\oplus}^3/r^4)$	2.1×10^{-9}	0.2	0.8	0.01
Ocean tides	≈ 0.1 Earth's tides	2.1×10^{-10}	0.02	0.08	0.001
General relativity	$(GM_{\oplus}/r^2)(GM_{\oplus}/c^2)(1/r)$	6.8×10^{-11}	0.008	0.09	0.04

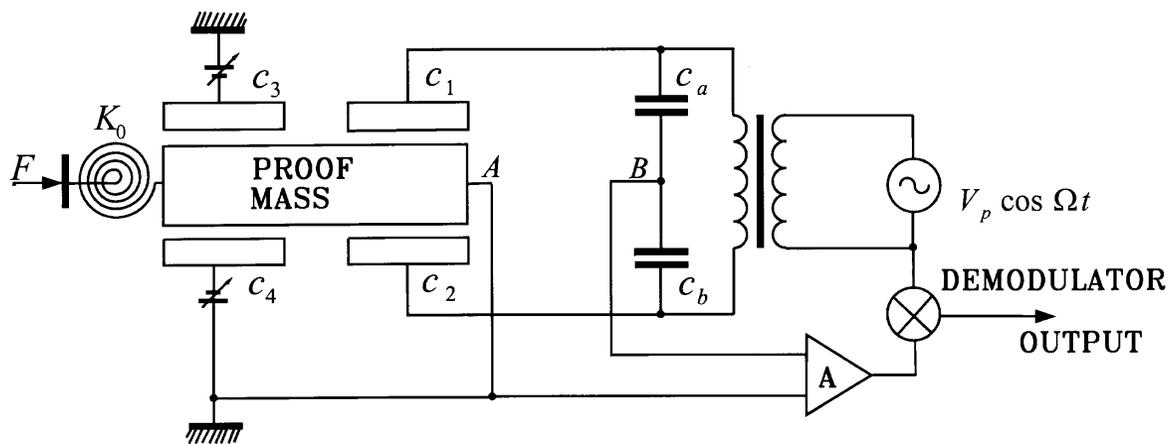
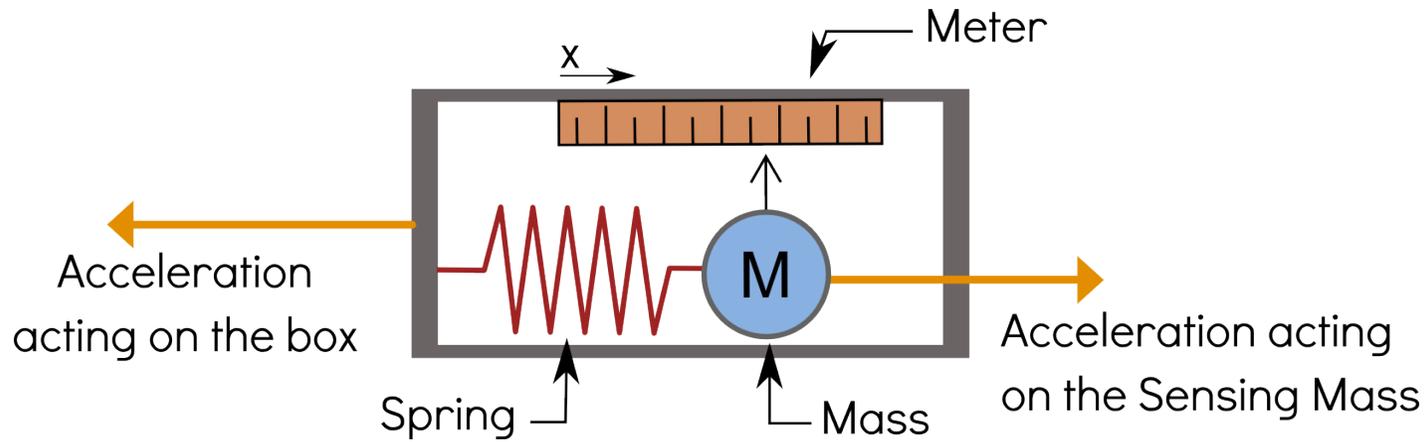
Acceleration term	Formula	GALILEO2 [m/s ²]	R [m]	T [m]	W [m]
Main non gravitational perturbations					
SRP	$A\Phi_{\odot}/Mc$	1.5×10^{-7}	116	279	8
Earth's albedo	$2A_{\oplus}(\pi R_{\oplus}^2/4\pi r^2)(A\Phi_{\odot}/Mc)$	1×10^{-9}	0.8	2.0	0.06
Y-bias	Y_0	1.2×10^{-9}	1.1	10	0.4
Power radiated by the antennas (*)	$\frac{P}{Mc}$	2×10^{-9}	0.05	3.5	0.06
Thermal effects: solar panels only	$(2\sigma A/3Mc)(\epsilon_1 T_1^4 - \epsilon_2 T_2^4)$	4×10^{-10}	0.5	4.5	0.01

(*) We assumed a misalignment of the antenna of about 1°

$a = 29600$ km semi-major axis

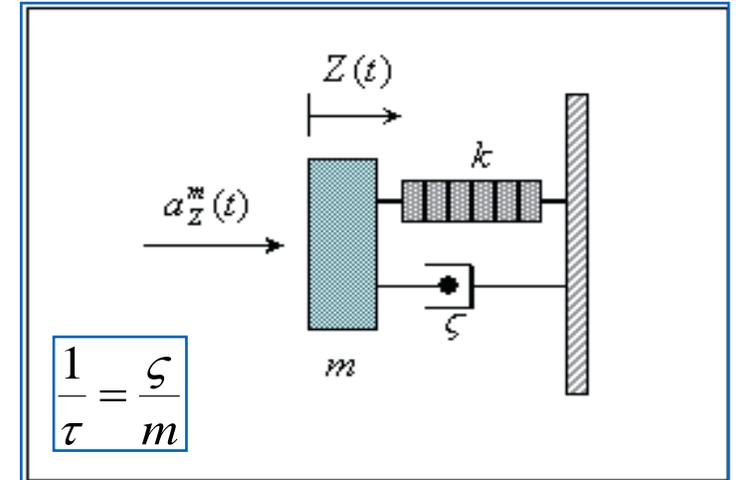
Accelerometer: measurements and physical characteristics

Principle of operation of a spring accelerometer



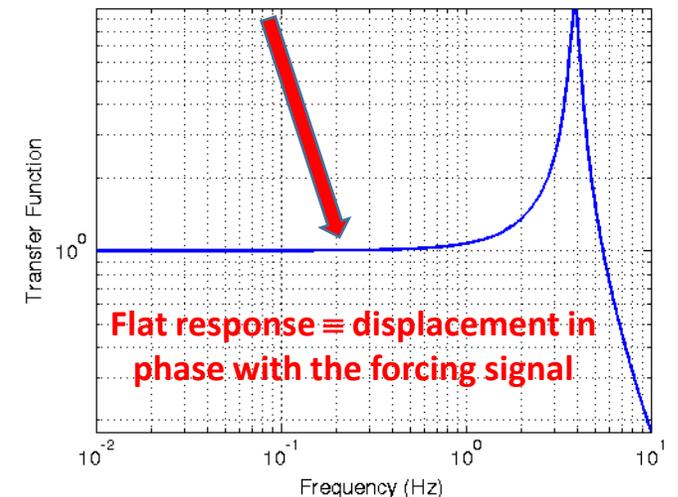
Electrical diagram of one proof-mass pickup system

Forced harmonic oscillator



$$m\ddot{Z}(t) + \zeta\dot{Z}(t) + kZ(t) = F_Z(t)$$

$$\ddot{Z}(t) + \dot{Z}(t)/\tau + \omega_0^2 Z(t) = a_Z(t)$$



Accelerometer: measurements and physical characteristics

On board measurements

$$\ddot{\vec{r}} = -\nabla U(\vec{r}) + \vec{A}_{NGP}$$

$$\vec{a}_{accel} = \left(\vec{\nabla} \cdot \vec{g} \right) \vec{R} - \vec{\omega} \wedge (\vec{\omega} \wedge \vec{R}) - \dot{\vec{\omega}} \wedge \vec{R} - \vec{A}_{NGP} - \vec{a}_{CM} - \left. \frac{\Delta \vec{V}}{\Delta t} \right|_{Man.}$$

To obtain a **POD** we need to write the **equations of motion**, containing the **dynamical parameters** of interest, with respect to a reference point of the spacecraft

Usually, this point is the spacecraft center-of-mass (**CoM**)

1. **Non-gravitational accelerations (NGA)**

$$-\vec{A}_{NGP}$$

2. Accelerations due to **gravity gradients**

$$\left(\vec{\nabla} \cdot \vec{g} \right) \vec{R}$$

3. **Apparent accelerations**

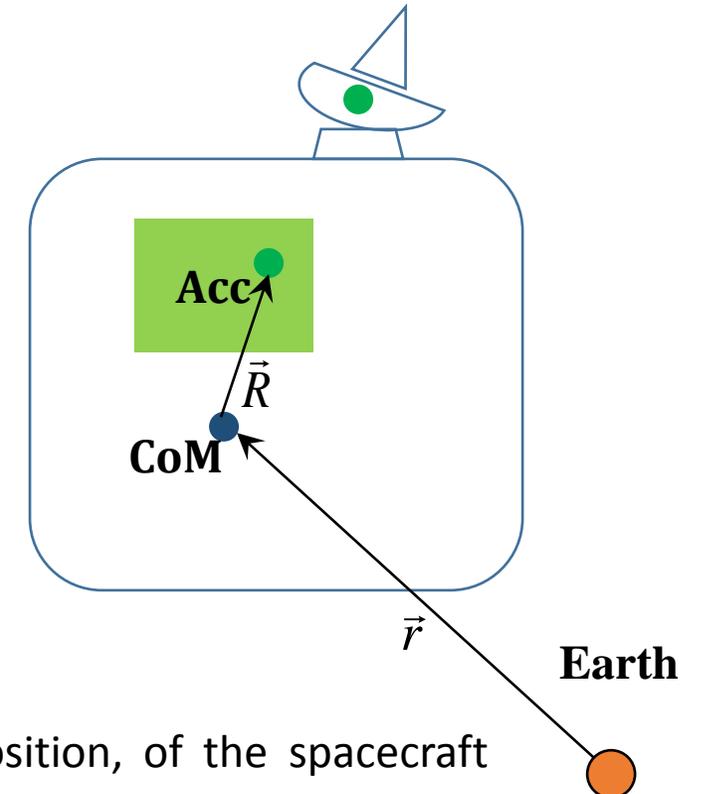
$$-\vec{\omega} \wedge (\vec{\omega} \wedge \vec{R}) - \dot{\vec{\omega}} \wedge \vec{R}$$

4. **Spacecraft center-of-mass accelerations**

$$-\vec{a}_{CM} = -2\vec{\omega} \wedge \dot{\vec{R}}_{rot} - \ddot{\vec{R}}_{rot}$$

5. Accelerations due to **thruster maneuvers**

$$\left. \frac{\Delta \vec{V}}{\Delta t} \right|_{Man.}$$



All these aspects impose requirements on the knowledge of the test masses position, of the spacecraft attitude, and on the spacecraft **CoM** drifts and accelerations

Accelerometer: measurements and physical characteristics

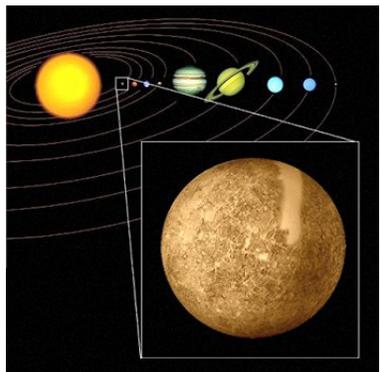
BepiColombo Radio Science Experiments (RSE)

The space mission **BepiColombo**, one of the Cornerstones of **ESA**, aims to perform:

1. a detailed study of the planet **Mercury** and its environment
2. a test of **Einstein's** General Relativity to an unprecedented level of accuracy

Launch window opens on July 10, 2017, arrival January 1, 2024
start of science February 2024:

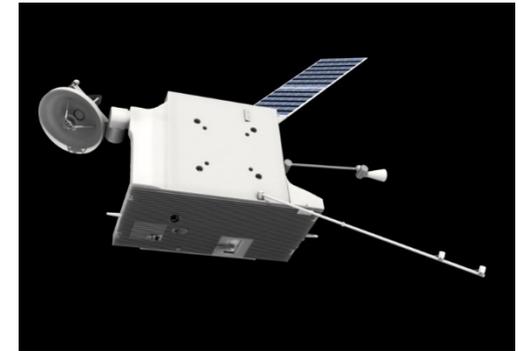
1 year of nominal duration + 1 year of extended mission



The **RSE** represents a complex mix of measurements and scientific objectives and, very interesting, it is not possible to separate them neatly in independent experiments.

However, we can distinguish:

- 1) a **gravimetry experiment**
- 2) a **rotation experiment**
- 3) a **relativity experiment**



Basically, on-board the MPO, the instruments used for these experiments are:

- Ka-band Transponder
- Star-Tracker
- High Resolution Camera
- Accelerometer

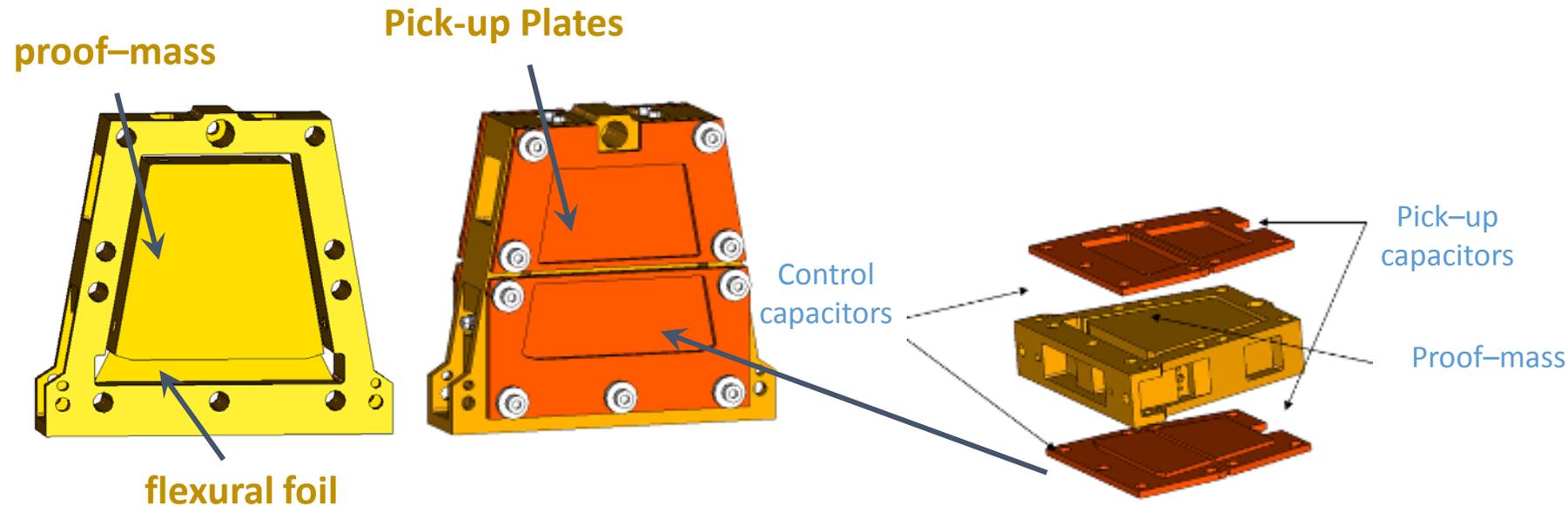
Accelerometer: measurements and physical characteristics

ISA (Italian Spring Accelerometer) role: measurement of the non-gravitational accelerations

- Indeed, the **modelling** depends on a set of **parameters** related with the physical properties of the satellite surface and structure, which will be **strongly influenced**, and with **unknown laws**, by the **strong radiation environment** in the surroundings of **Mercury**
- Therefore the **MPO** surface will reflect (in the visible) and re-radiate (in the infrared) in a very complex way. Then we have the shadowing effects ...
- **ISA** allows to remove the **NGA** from the equations of motion in such a way to reconstruct the **pure gravitational orbit** of a reference point of the **MPO** spacecraft

Each ISA sensing element is a flexural harmonic oscillator presently obtained by working a single piece of Al 7075.

The pick-up system of the accelerometer is a capacitive one



Accelerometer: measurements and physical characteristics

ISA main characteristics

ISA oscillator parameters:

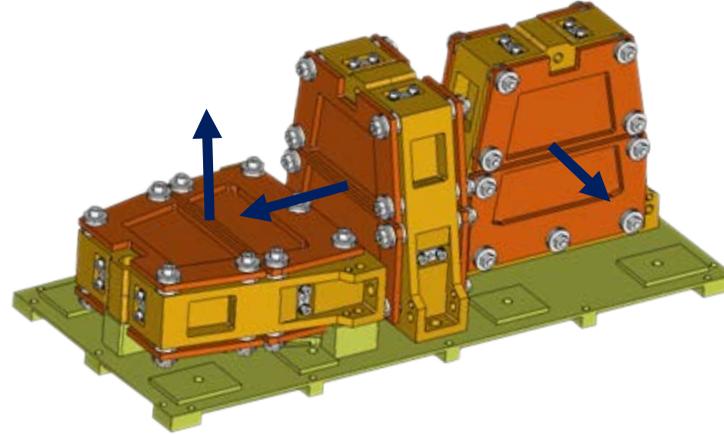
Mass	200 g
Resonance frequency	3.9 Hz
Mechanical quality factor (Q)	10

ISA performance:

Measurement bandwidth	$3 \times 10^{-5} \div 1 \times 10^{-1}$ Hz
Intrinsic noise	1×10^{-9} m/s ² /√Hz
Measurement accuracy	1×10^{-8} m/s ²
Dynamics	300×10^{-8} m/s ²
A/D converter saturation	3000×10^{-8} m/s ²

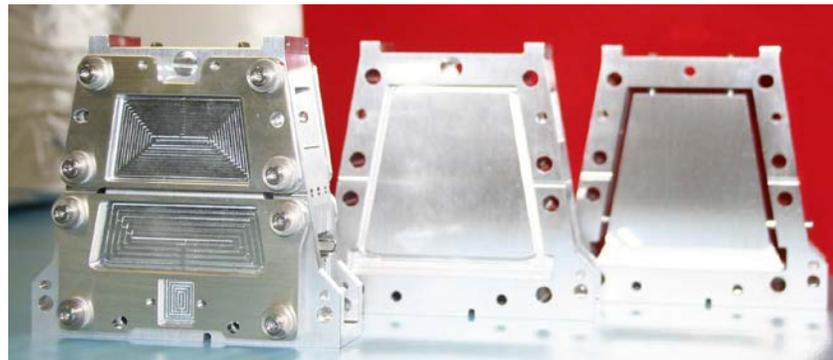
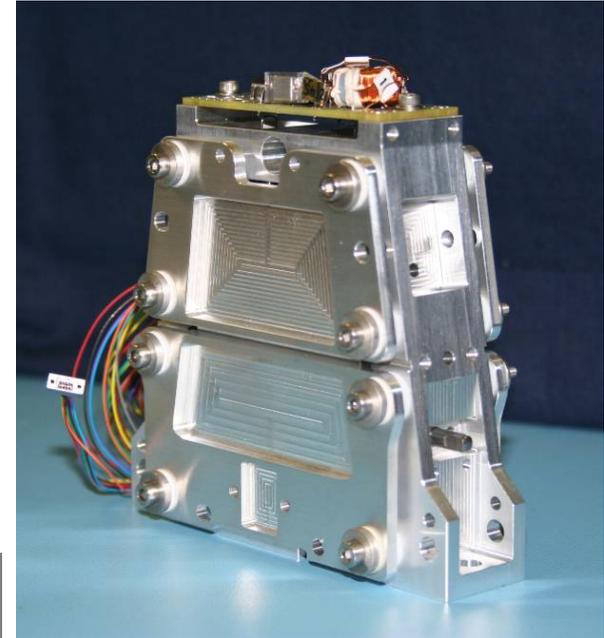
Temperature variations:

Mercury half sidereal period (44 days)	25°C p-p
MPO orbital period (2.325 h)	4°C p-p
Random noise	10°C /√Hz



ISA thermal stability:

Sensor thermal sensitivity	2.5×10^{-9} m/s ² /°C
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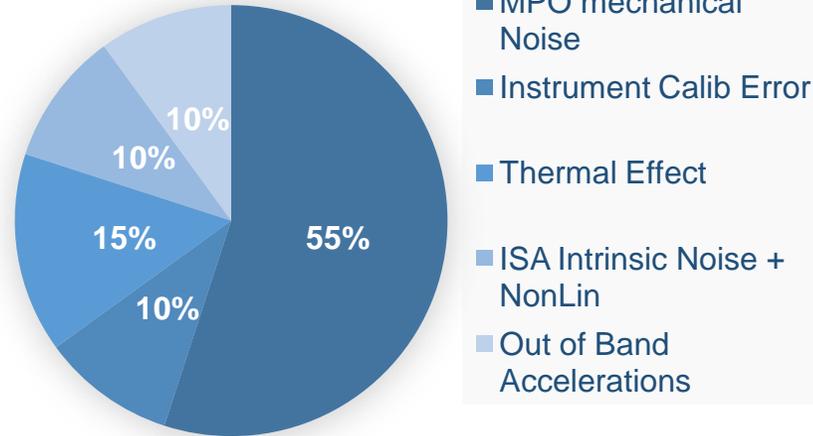


Accelerometer: measurements and physical characteristics

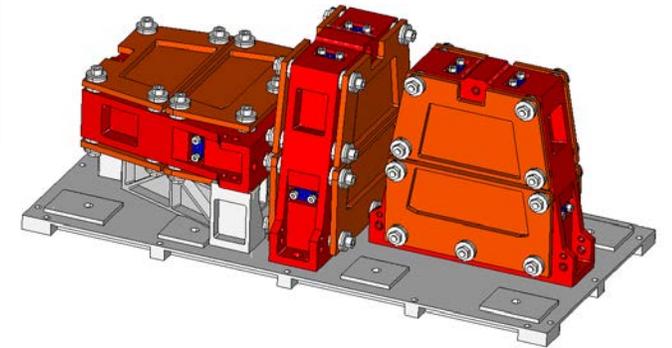
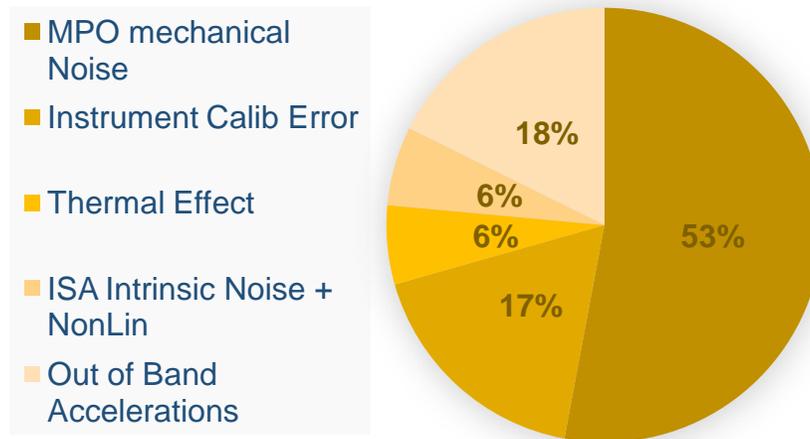
Error budget

Error term	Error Share
MPO mechanical noise + Data reduction residuals <small>Errors related to the reconstruction of acceleration vector at ISA vertex. Due to ancillary data knowledge accuracy. (MPO motion, attitude, ISA geometry,...)</small>	Periodic 55% Random 90%
Instrument Calibration errors	Periodic 10% Random Negl.
Thermal effects	Periodic 15% Random 30%
ISA intrinsic noise <small>(FEE noise, Brownian Noise, dissipation in damping resistors,...)</small> + ISA response to in-band accelerations <small>(TF flatness, Non linearity, Crosstalk)</small>	Periodic 10% Random 10%
Out of band accelerations effects	Periodic 10% Random 30%

Periodic



Random



Accelerometer: measurements and physical characteristics

Under an **ESA** contract, we started a collaboration with our Polish colleagues of **SRC-PAS** Warsaw in order to improve the final **POD** of a **GALILEO2-sat** by the use of an onboard accelerometer

- The final goal is to verify, by means of *ad hoc* simulations, the degree of improvement obtainable by means of the accelerometer readings with respect to the current models for the **NGPs** available in the literature (**SRC-PAS**)
- One of our starting activities has been to provide **SRC-PAS** with a preliminary list of requirements in terms of:
 - Measurement band
 - Measurement noise
 - Accuracy
 - Precision
 - Amplitude of the maximum acceleration to be measured

Simplified model for a GALILEO2-sat and for its orbit

The dimensions and mass of a **GALILEO2-sat** that have been used in the simulations are:

- dry mass 1528 kg
- spacecraft body cross section 5.82 m²
- Solar array area 44 m²

→ $\frac{A}{M} \cong 3.26 \times 10^{-2} \text{ m}^2/\text{kg}$

≈ 47 times LAGEOS A/M ratio
 ≈ 122 times LARES A/M ratio

Order-of-magnitude: SRP and Albedo RP

$$a_{\odot} = C_R \frac{A}{M} \frac{\Phi_{\odot}}{c} \left(\frac{1 \text{ AU}}{r_{\odot}} \right)^2 \approx 1.55 \times 10^{-7} \text{ m/s}^2$$

$$1 \leq C_R \leq 2$$

$C_R = 1$ perfect absorption
 $C_R \approx 1.21$ solar panels
 $C_R \approx 1.30$ HGA
 $C_R = 2$ specular reflection

Solar irradiance
 @ 1 AU
 $\Phi_{\odot} \cong 1380 \text{ W/m}^2$

$$a_{\oplus} = 2A_{\oplus} \frac{\pi R_{\oplus}^2}{4\pi r^2} a_{\odot} \approx 1 \times 10^{-9} \text{ m/s}^2$$

$A_{\oplus} \approx 0.3$ Average Bond albedo coefficient

Simplified model for a GALILEO2-sat and for its orbit

We are interested to evaluate the **NGPs** accelerations due to direct **SRP** and Earth's albedo radiation pressure (**ARP**) over a few orbits of a spacecraft in order to fix a preliminary list for the accelerometer requirements. In particular we assumed:

1. An ideal 2-body nominal orbit (a, e, I, P) perturbed by the **NGPs**
2. An integration step size of 0.01° (corresponding to about 1.408 s)
3. Three consecutive orbits to evaluate the spectral content of each acceleration component in the Gauss co-moving frame (R, T, W)
4. The position of the Sun, of the ascending node and of the argument of pericenter have always been considered fixed during an orbital revolution of the spacecraft

Nominal orbit:

$a = 29600$ km	semi-major axis
$e = 0.001$	eccentricity
$I = 56^\circ$	inclination
$P = 50681.42$ s	orbital period

$$\begin{cases} \dot{\Omega} \cong -1.43273 \times 10^{-3} \text{ deg/day} \\ \dot{\omega} \cong -2.58819 \times 10^{-2} \text{ deg/day} \\ \dot{\lambda}_{\odot} \cong +9.856473 \times 10^{-1} \text{ deg/day} \end{cases}$$

Rates for the angular variables

Simulations for SRP and Albedo effects

In the simulations we considered:

- A cannon ball model for the **SRP** and we considered the Sun an extended sources in order to take into account the fraction of sunlight that heats the spacecraft surface during the penumbra transition:

$$\vec{a}_{\odot} = -\mu C_R \frac{A}{M} \frac{\Phi_{\odot}}{c} \left(\frac{1AU}{r_{\odot}} \right)^2 \hat{s}$$

$$\begin{array}{ll} \mu = 1 & \text{full sunlight} \\ \mu = 0 & \text{umbra} \\ 0 < \mu < 1 & \text{penumbra} \end{array}$$

- In the case of the albedo we integrated twice:
 - Over the spherical cap seen by the spacecraft
 - Over one orbital revolution of the spacecraft
- We follow Rubincam and Weiss *Celest Mech* **38** (1986); Rubincam et al. *JGR* **92** (1987); Lucchesi and Farinella *JGR* **97** (1992) in order to model the albedo effects:

$$\vec{a}_{alb} = a_{\odot} \varrho^2 f_r A_{\oplus} \cos z_{\odot} \frac{(\cos \theta - \rho)}{(1 - 2\rho \cos \theta + \rho^2)^2} \frac{d\Gamma}{\pi R_{\oplus}^2} \cdot \left\{ \begin{array}{l} (\sin \theta_G \cos \lambda_G - \rho \sin \theta \cos \lambda) \hat{x} \\ (\sin \theta_G \sin \lambda_G - \rho \sin \theta \sin \lambda) \hat{y} \\ (\cos \theta_G - \rho \cos \theta) \hat{z} \end{array} \right\}$$

Simulations for SRP and Albedo effects

In the simulations:

- We considered different geometrical configuration of the Sun λ_{\odot} with respect to the orbital plane Ω in order to simulate:

- different heights of the Sun β_{\odot} with respect to the orbital plane
- different durations of the eclipses

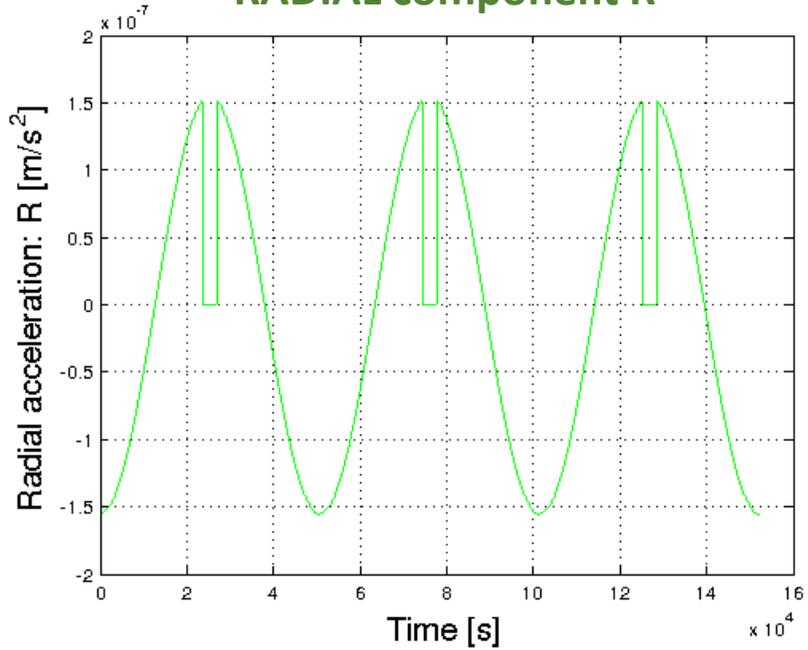
$$0 \leq \beta_{\odot} \leq \beta_{\odot}^{max} = \begin{cases} I + \varepsilon_{\odot} = 79.45^{\circ} \\ I - \varepsilon_{\odot} = 32.55^{\circ} \end{cases}$$

- We performed the spectral analysis (**FFT**) of the components of the perturbing accelerations in order to preliminary fix:
 - the main higher harmonics with respect to the spectral line at the orbital period
 - their amplitudes
 - the upper limit of the accelerometer measurement bandwidth

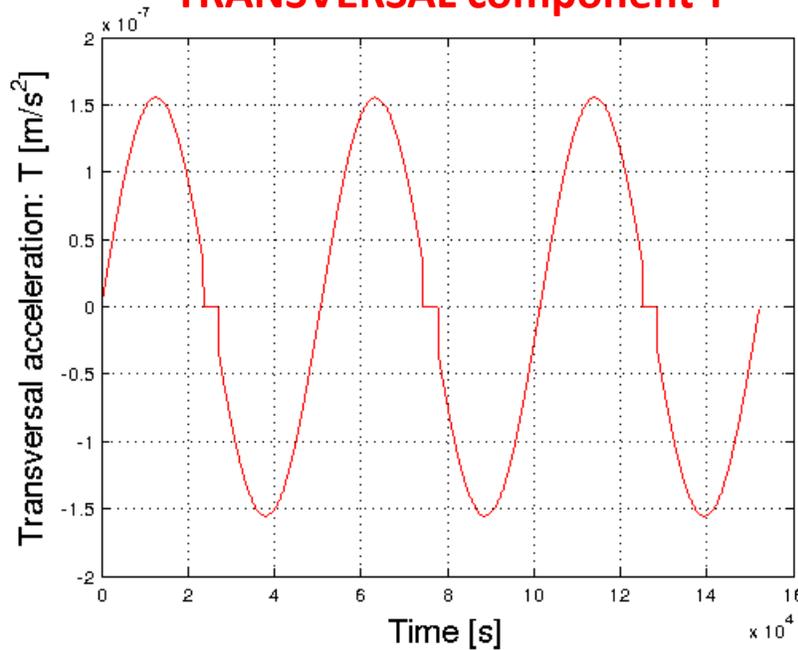
Simulations for SRP and Albedo effects

SRP results: case $\Omega = \lambda_{\odot} = 0 \rightarrow \beta_{\odot} \cong 0$

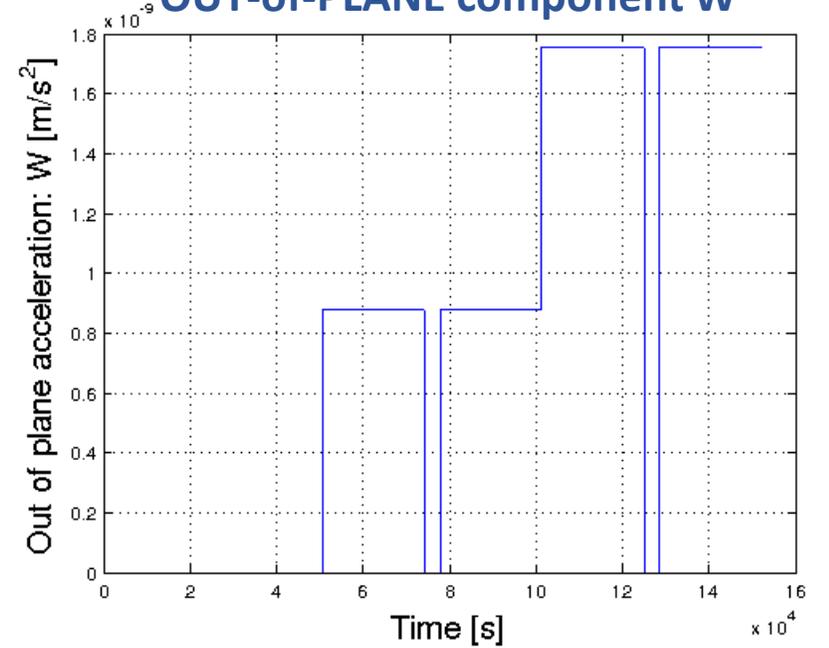
RADIAL component R



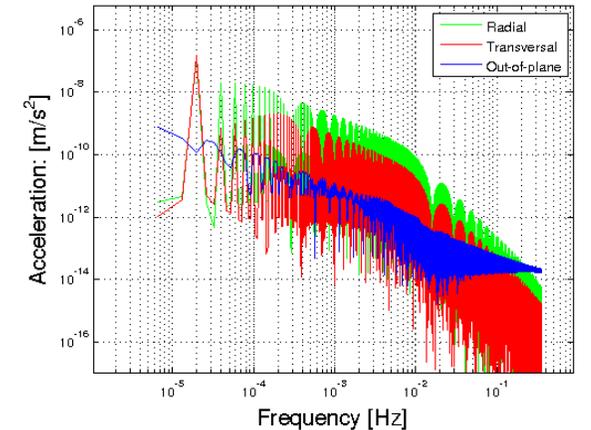
TRANSVERSAL component T



OUT-of-PLANE component W



FFT

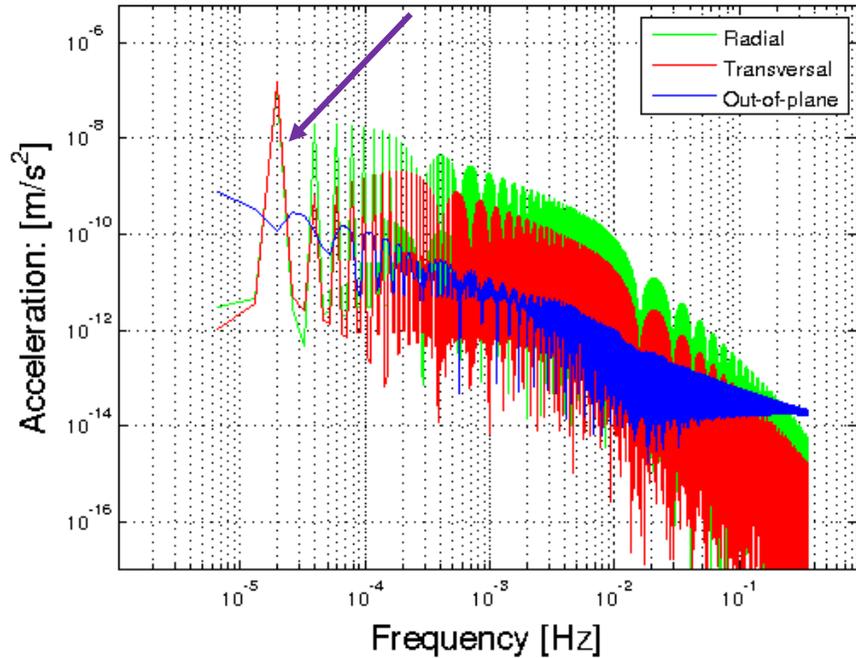


Acceleration	Mean	Max	Min	Peak- to- peak	Amplitude FFT @P
R	-1.06×10^{-8}	$+1.515 \times 10^{-7}$	-1.553×10^{-7}	3.068×10^{-7}	1.342×10^{-7}
T	$+4.36 \times 10^{-15}$	$+1.553 \times 10^{-7}$	-1.553×10^{-7}	3.106×10^{-7}	1.550×10^{-7}
W	$+8.17 \times 10^{-10}$	$+1.75 \times 10^{-9}$	0	1.75×10^{-9}	1.20×10^{-10}

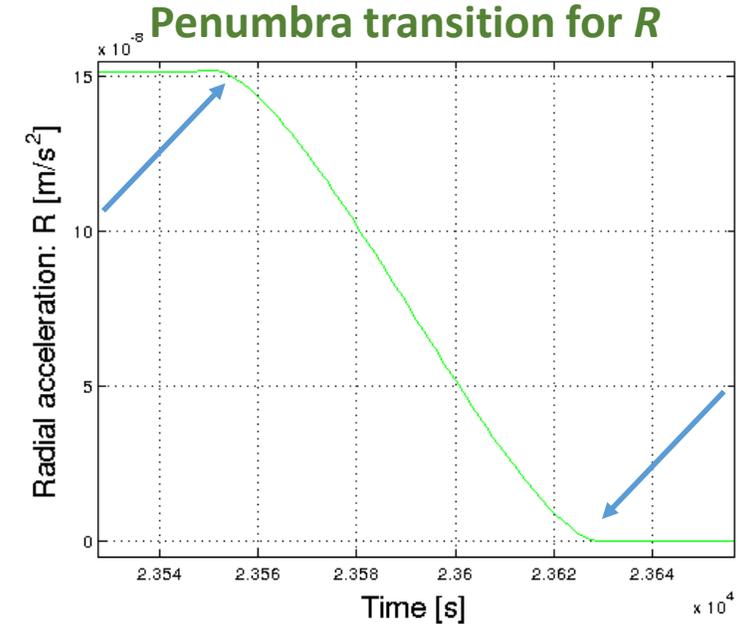
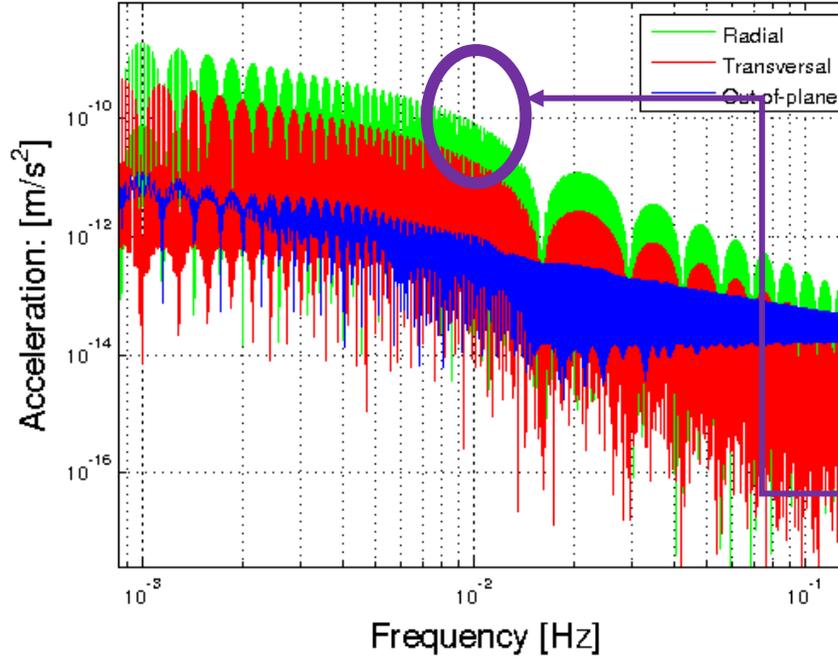
Simulations for SRP and Albedo effects

SRP results: case $\Omega = \lambda_{\odot} = 0 \rightarrow \beta_{\odot} \cong 0$

Fast Fourier Transform (FFT)



FFT details around 10⁻² Hz



Penumbra $\cong 76$ s
Eclipses $\cong 57$ min

$\cong 10^{-10} \text{ m/s}^2 @ 10^{-2} \text{ Hz}$

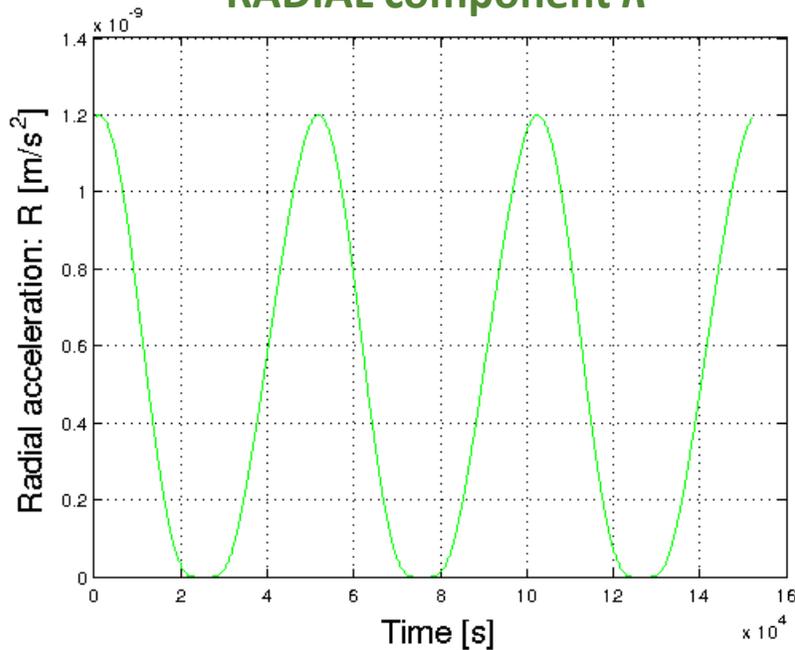
Possible upper limit of the accelerometer measurement band

- For the **Radial** and **Transversal** accelerations we have a main line at the inverse of the orbital period ($\nu_{\text{orb}} \cong 1.973 \times 10^{-5} \text{ Hz}$) plus higher order harmonics, which are an integer multiple of the harmonic at the orbital period
- For the **Out-of-Plane** component, the FFT is less representative of its real behavior because of the underlying approximations ...

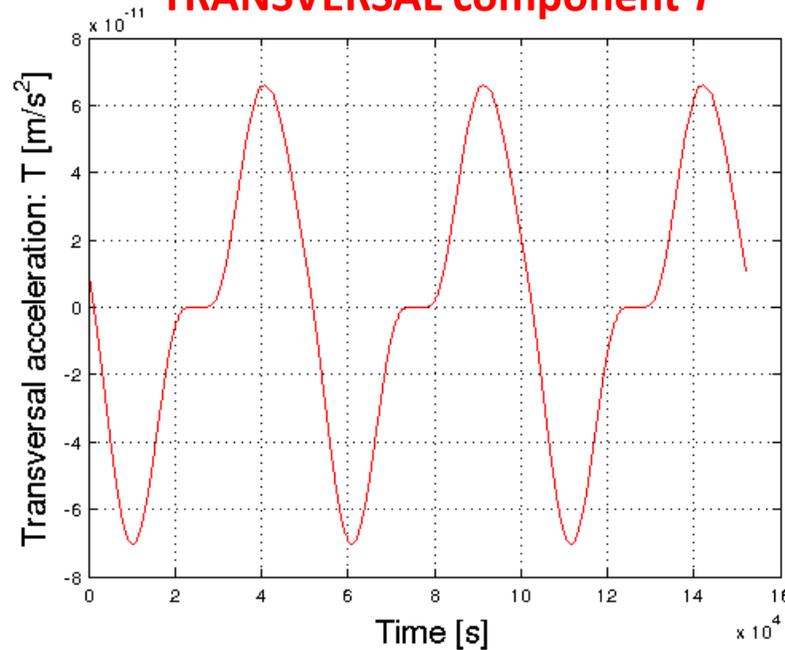
Simulations for SRP and Albedo effects

Earth's Albedo results: case $\Omega = \lambda_{\odot} = 0 \rightarrow \beta_{\odot} \cong 0$

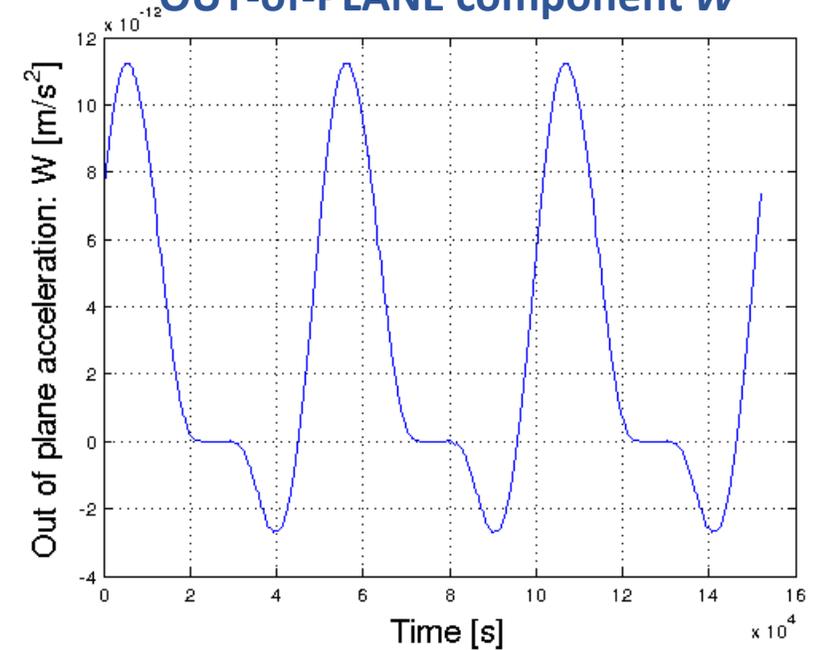
RADIAL component R



TRANSVERSAL component T



OUT-of-PLANE component W



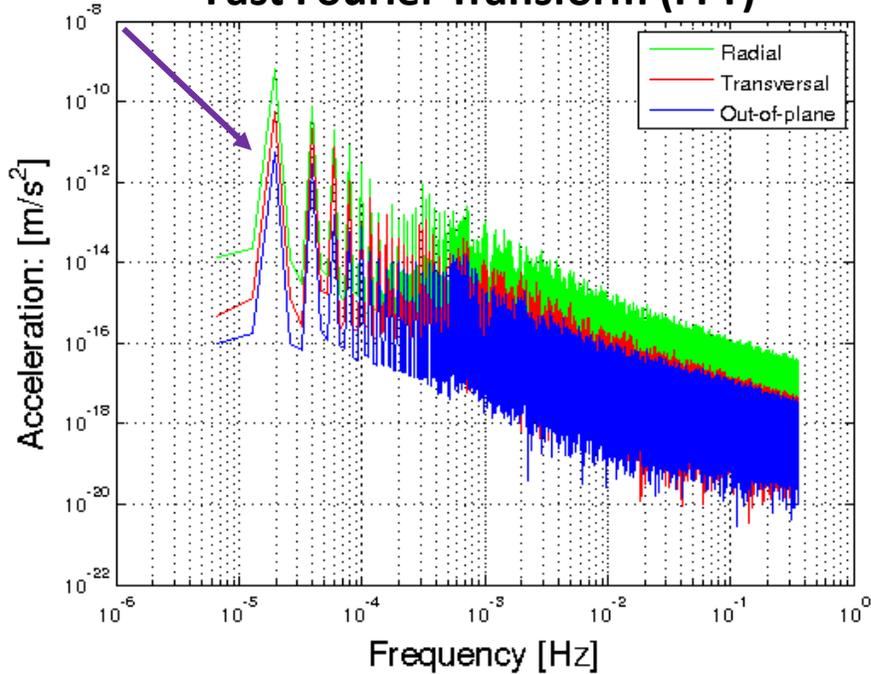
It is clear the much smaller impact of the albedo acceleration with respect to that of the **SRP**:

- the amplitudes of the **Radial** and **Out-of-Plane** accelerations of Earth's albedo are more than two orders of magnitude smaller than the corresponding amplitudes from the direct **SRP**
- the amplitude of the **Transversal** acceleration of albedo is more than three orders of magnitude smaller than that from the direct **SRP**

Simulations for SRP and Albedo effects

Earth's Albedo results: case $\Omega = \lambda_{\odot} = 0 \rightarrow \beta_{\odot} \cong 0$

Fast Fourier Transform (FFT)



The three components of the **Albedo** acceleration have a quasi-sinusoidal behavior. From their **FFT** it is apparent:

- A main component at the inverse of the orbital period
- Higher-order harmonics characterized by frequencies at integer multiples of the main spectral line
- Very small amplitudes, also at the orbital period

Acceleration	Mean	Max	Min	Peak-to-Peak	Amplitude FFT @P
R	$+5.17 \times 10^{-10}$	$+1.20 \times 10^{-9}$	0	$+1.20 \times 10^{-9}$	6.15×10^{-10}
T	$+1.47 \times 10^{-12}$	$+6.57 \times 10^{-11}$	-7.04×10^{-11}	1.36×10^{-10}	5.37×10^{-11}
W	$+2.58 \times 10^{-12}$	$+1.13 \times 10^{-11}$	-3.00×10^{-12}	1.43×10^{-11}	5.59×10^{-12}

Preliminary results in terms of accelerometer performance

From previous assumptions/simulations we are able to provide the main requirements for an onboard accelerometer for what regards:

- Measurement frequency band
- Sensitivity and accuracy (to improve the **POD** with respect to the current models)
- Maximum amplitude for the in-band signal (it contributes to fix the dynamics of the accelerometer)

	ISA-GALILEO2	ISA-BepiColombo
Measurement band (*)	$1.9 \times 10^{-5} \text{ Hz} \text{ — } 1 \times 10^{-2} \text{ Hz}$	$3 \times 10^{-5} \text{ Hz} \text{ — } 1.0 \times 10^{-1} \text{ Hz}$
Amplitude max. acceleration (**)	$2 \times 10^{-7} \text{ m/s}^2$	$3.0 \times 10^{-6} \text{ m/s}^2$
Measurements noise floor (***)	$\leq 1 \times 10^{-9} \text{ m/s}^2/\sqrt{\text{Hz}}$	$1 \times 10^{-9} \text{ m/s}^2/\sqrt{\text{Hz}}$
Accuracy	$\approx 1 \times 10^{-9} \text{ m/s}^2$	$1.0 \times 10^{-8} \text{ m/s}^2$
Precision	$< 10^{-10} \text{ m/s}^2$	$< 10^{-9} \text{ m/s}^2$

(*) The lower limit should contain the frequency corresponding to the orbital period: $\nu_{\text{orb}} \cong 1.973 \times 10^{-5} \text{ Hz}$

(**) Summarizes the contribution of the NGPs plus the gravity gradients and apparent accelerations

(***) Superposition of the accelerometer noise + noise coming from the external environment

Conclusions

With regard to **ESA** request of possible **POD** improvements for next generation of **GALILEO** satellites by the use of an onboard accelerometer, we have shown some of the results of the preliminary activities performed at **IAPS/INAF** in term of:

- Spectral content of the accelerations (measurement band)
- Accuracy and precision of the measurements
- Maximum acceleration to be measured in order to fix the dynamic and, consequently the saturation level (both electronics and mechanics)

Forthcoming activities will focus on the following issues:

- provide to **SRC-PAS** the accelerometer error budget (**IAPS/INAF**)
- specify the requirements of the accelerometer in terms of an experimental activity based on bread boards (**AGI**)
- Provide a **POD** of a **GALILEO2-sat** with simulated data of the accelerometer readings and errors and compare the results with those of a **POD** based on current models of the **NGPs** (**SRC-PAS**)

Accelerometer: measurements and physical characteristics

